

REVIEW OF CAMOUFLAGE ASSESSMENT TECHNIQUES

Lex Toet & Maarten Hogervorst



OVERVIEW

- › Psychophysical evaluation methods:
 - › Field vs lab studies
 - › Detection and recognition range
 - › Search & detection performance
 - › Visual conspicuity
 - › Subjective blending score
 - › Ranking & paired comparison
 - › Eye tracking
 - › Masked priming
 - › Fixation locked ERPs

- › Computational evaluation methods:
 - › Saliency models
 - › Clutter and target signature metrics
 - › Search models

- › New developments and Future challenges

PSYCHOPHYSICAL EVALUATION METHODS : FIELD VS LAB STUDIES

	Field	Lab
Nr of conditions, locations, observers	Few	Many
Control over conditions	No control	Full control
Variation in performance across conditions	Large	Small
Time required	Long	Short
Effort	Labour intensive	Easy
Logistics	Complex	Simple
Costs	High	Low

But:

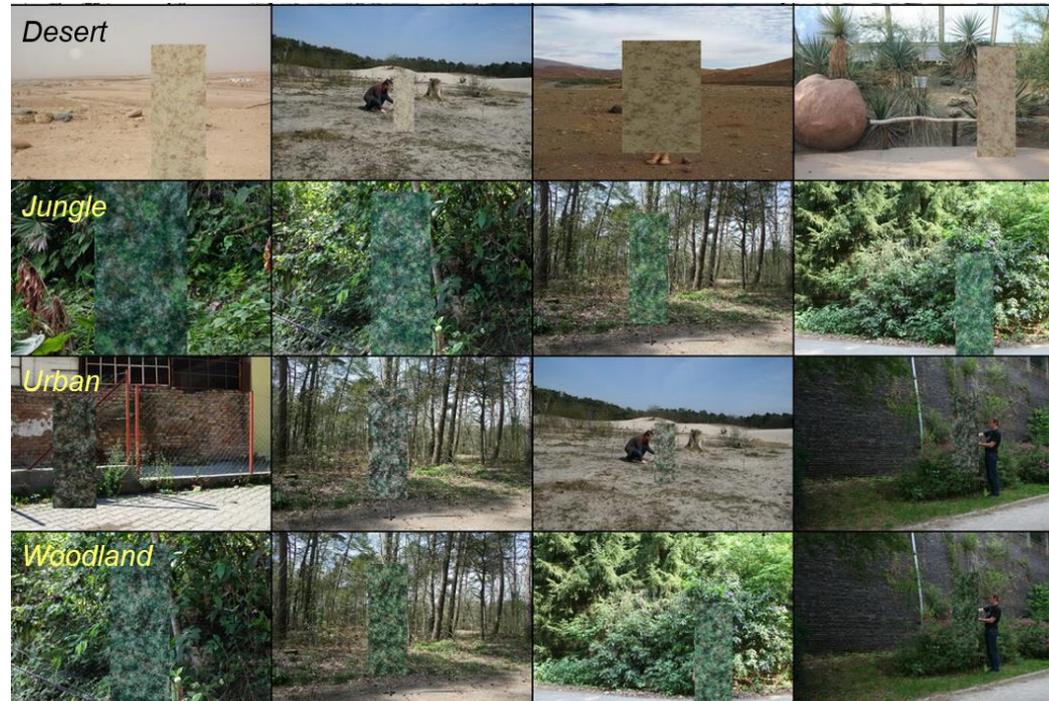
lab studies require validation with field data to establish link with real-world performance.

PSYCHOPHYSICAL EVALUATION METHODS : FIELD VS LAB STUDIES



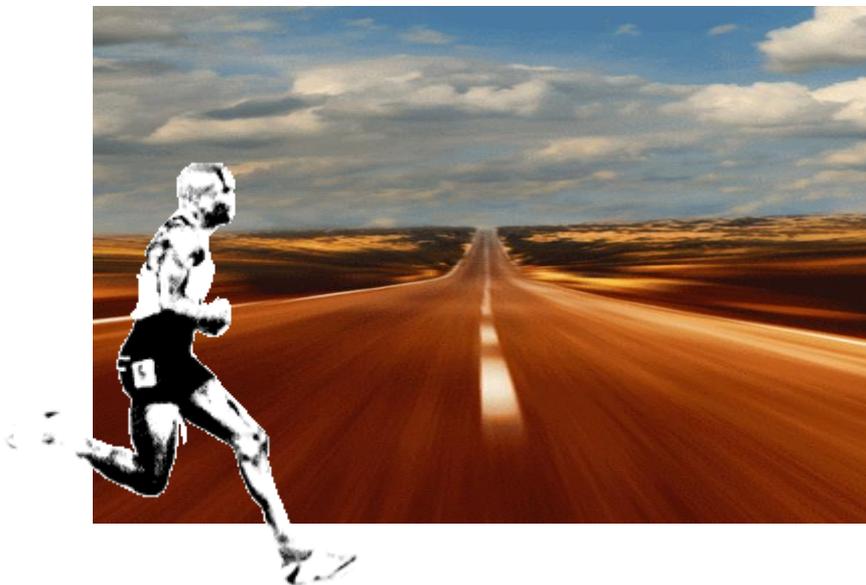
PSYCHOPHYSICAL EVALUATION METHODS : PHOTOSIMULATION STUDIES

- › Easy to study performance of targets in different backgrounds



PSYCHOPHYSICAL EVALUATION METHODS : DETECTION AND RECOGNITION RANGE

Field



Lab



PSYCHOPHYSICAL EVALUATION METHODS : SEARCH & DETECTION PERFORMANCE

Field trial



Lab experiment



PSYCHOPHYSICAL EVALUATION METHODS : SEARCH & DETECTION PERFORMANCE

Field trial



Lab experiment



PSYCHOPHYSICAL EVALUATION METHODS : SEARCH & DETECTION PERFORMANCE

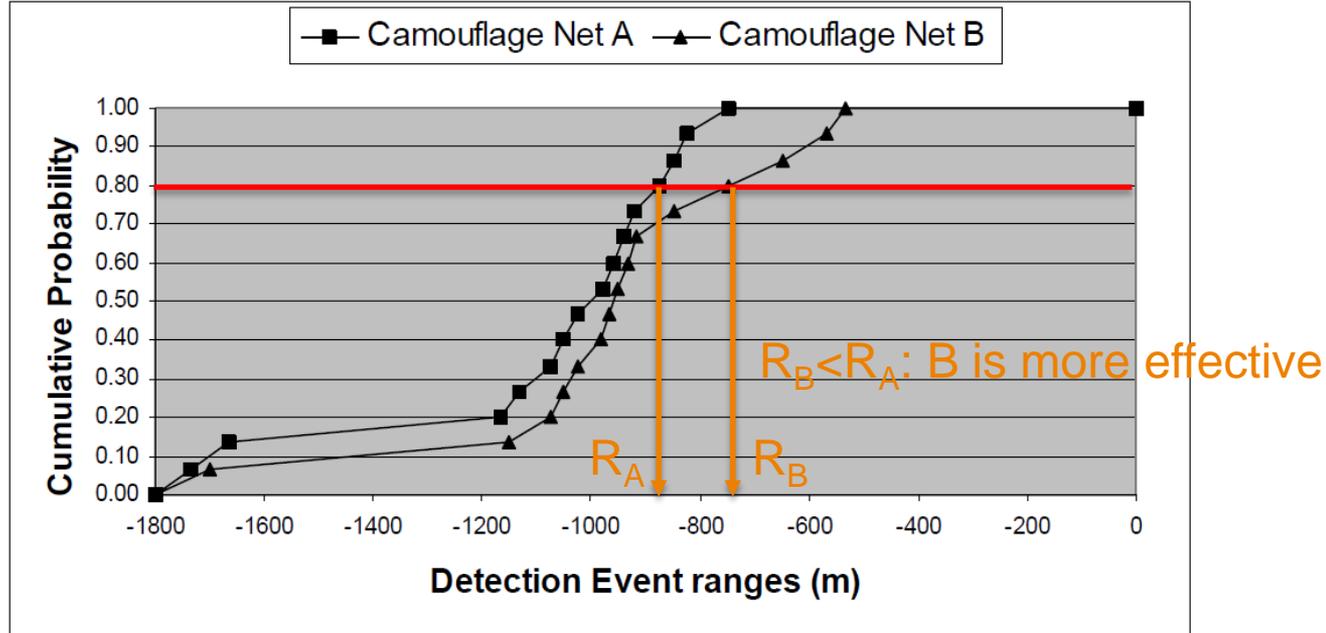
Field trial



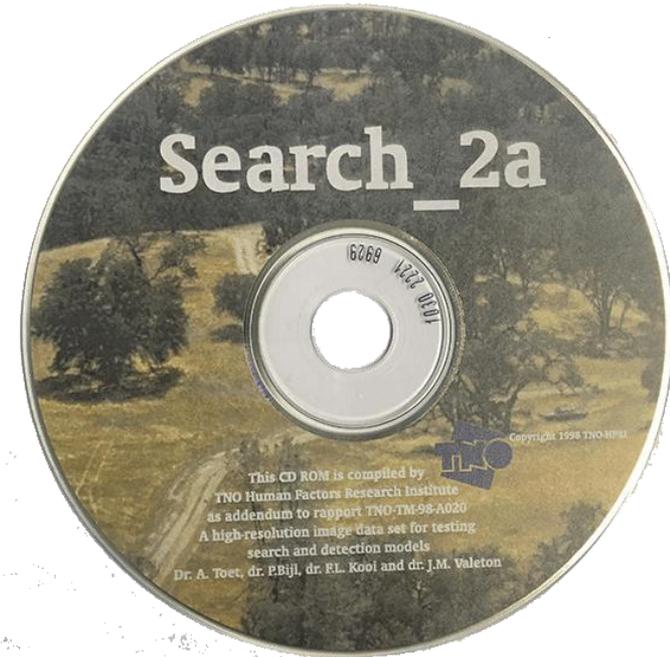
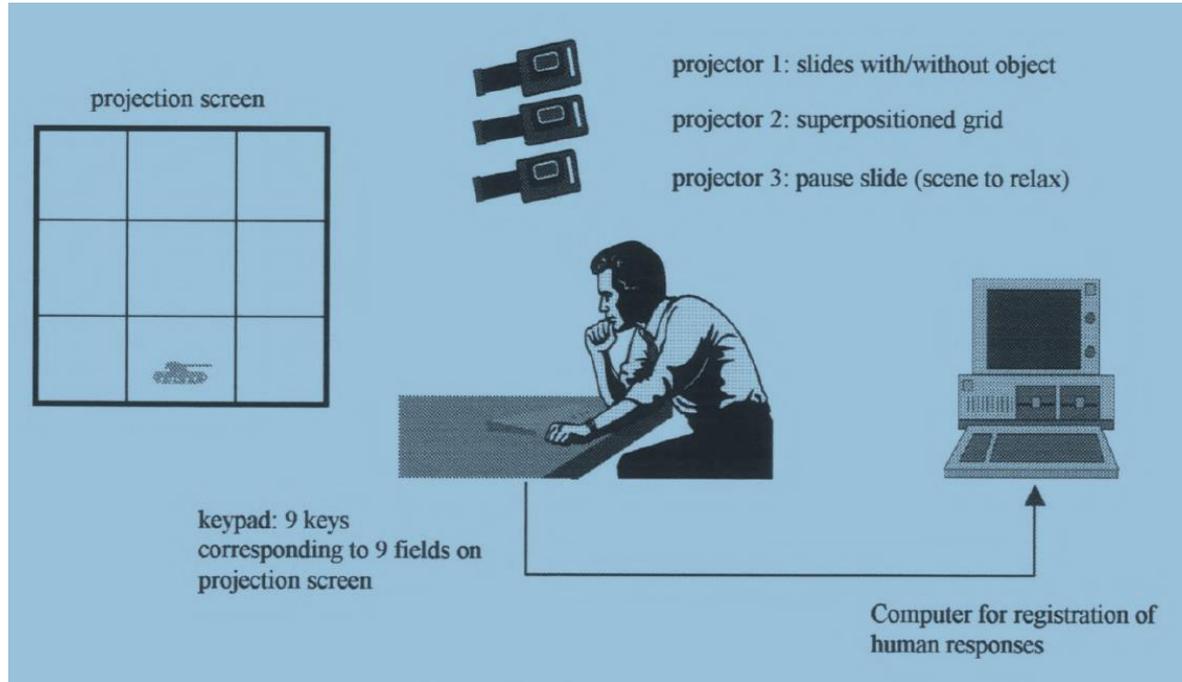
Lab experiment



PSYCHOPHYSICAL EVALUATION METHODS : DETECTION AND RECOGNITION RANGE



PSYCHOPHYSICAL EVALUATION METHODS : SEARCH & DETECTION



PSYCHOPHYSICAL EVALUATION METHODS : SEARCH & DETECTION PERFORMANCE

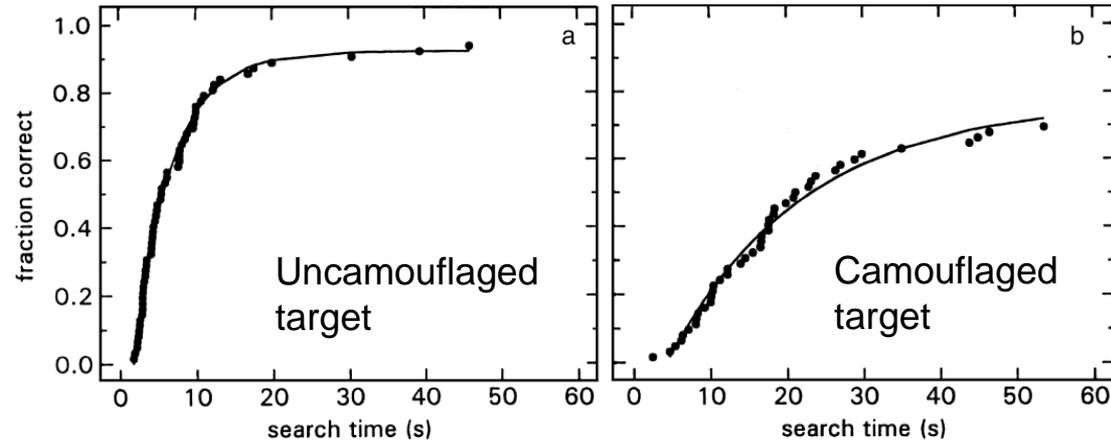
- › Performance metrics:
 - › Mean search time
 - › Detection probability

$$P_d(t) = P_\infty \left[1 - e^{-(t-t_r)/\tau} \right]$$

P_∞ = prob. to find target given unlimited time

t_r = minimal response time

τ = mean search time



PSYCHOPHYSICAL EVALUATION METHODS :

FOV SEARCH ON PANORAMIC IMAGES

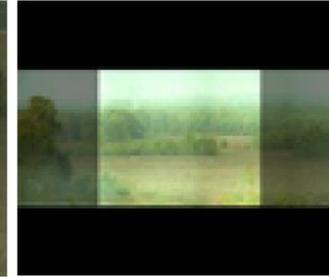
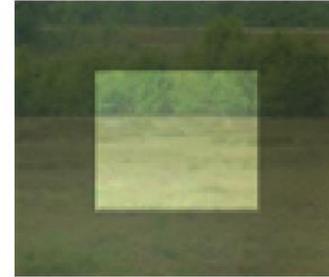
large window

small window

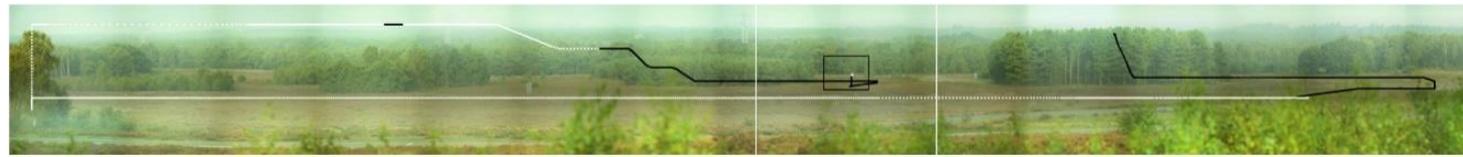
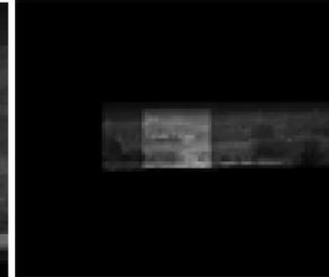
large zoom

small zoom

visual



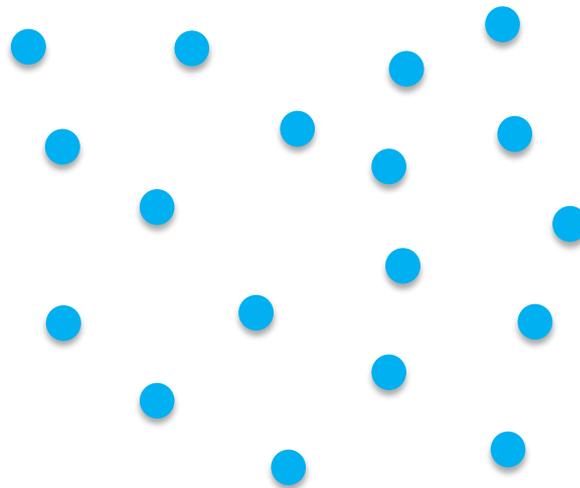
thermal



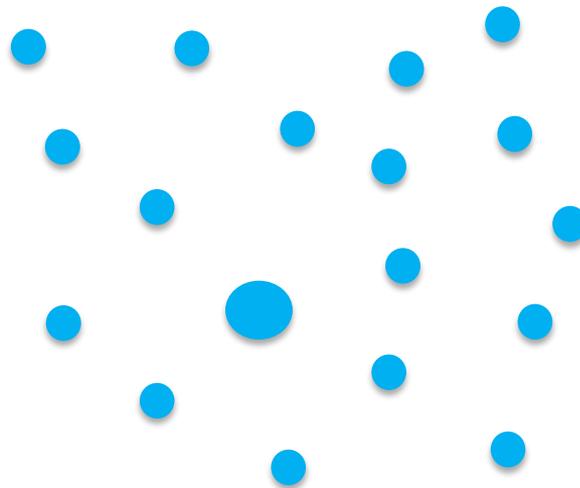
PSYCHOPHYSICAL EVALUATION METHODS : VISUAL CONSPICUITY



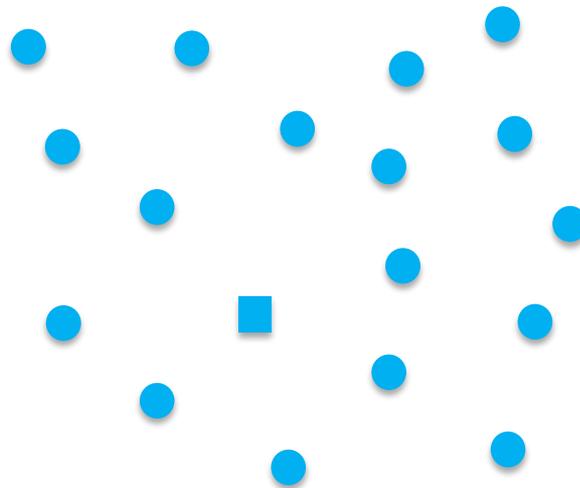
VISUAL CONSPICUITY



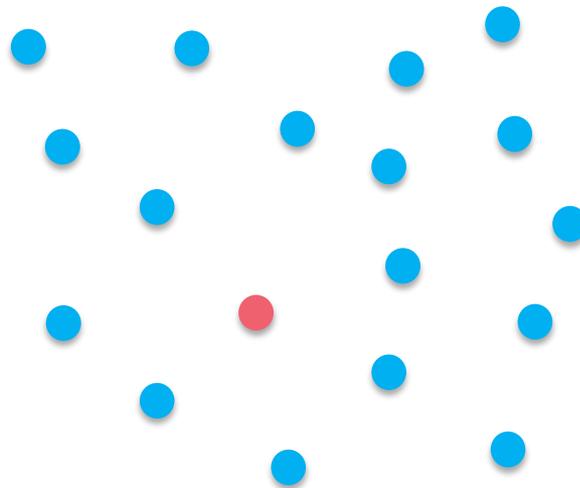
VISUAL CONSPICUITY



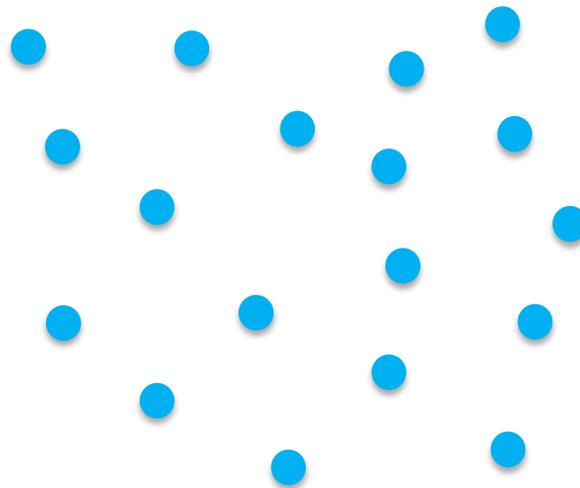
VISUAL CONSPICUITY



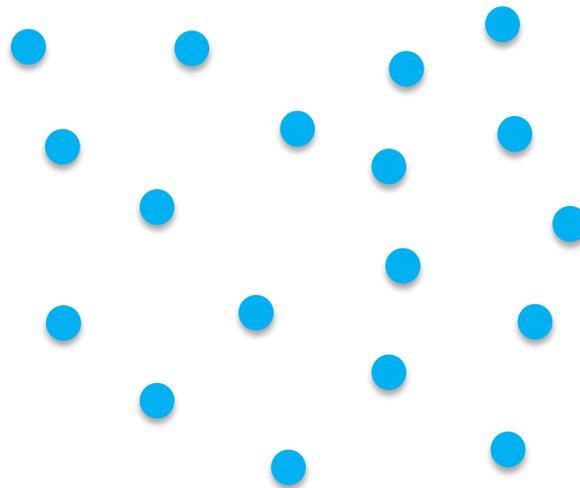
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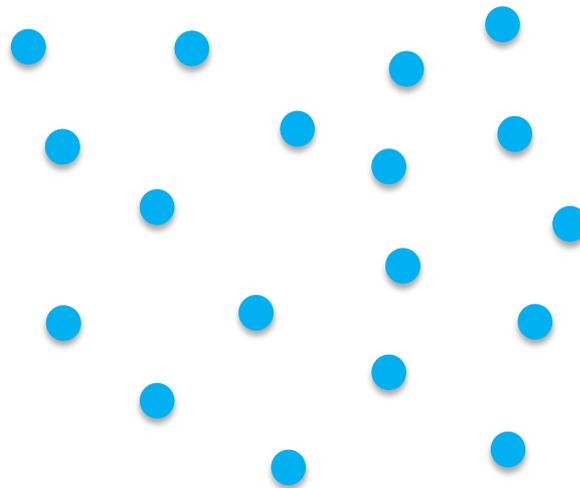
VISUAL CONSPICUITY



VISUAL CONSPICUITY



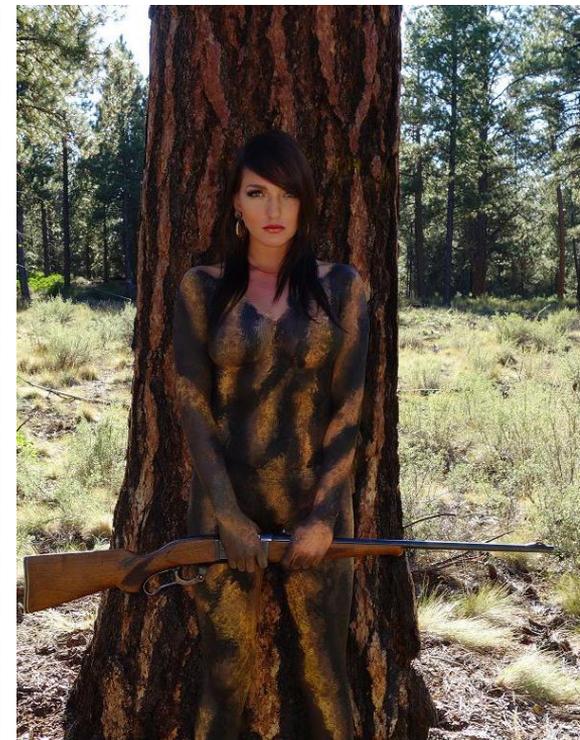
VISUAL CONSPICUITY



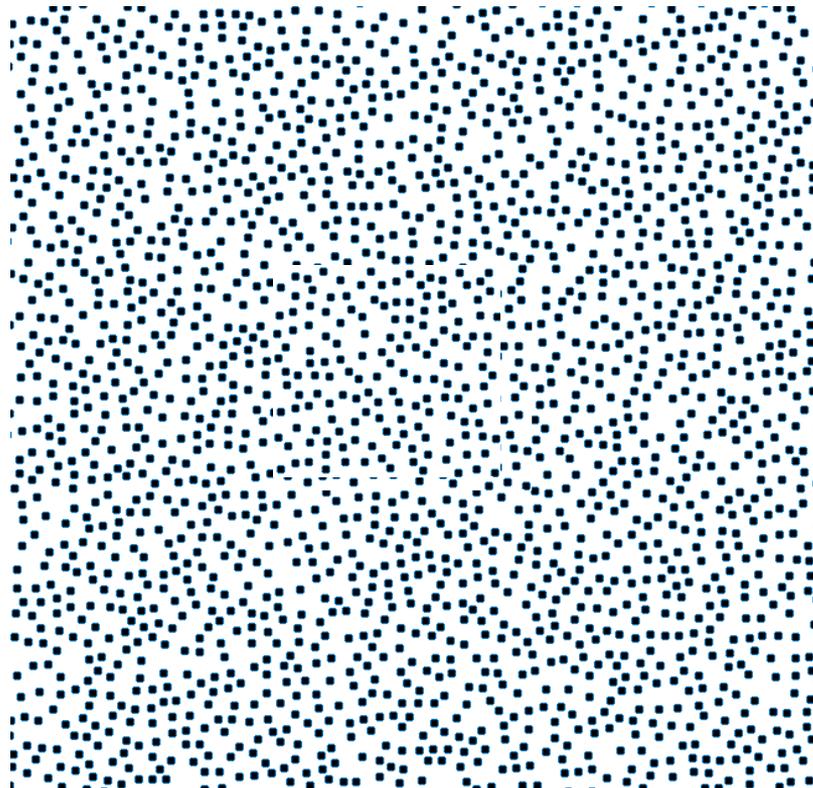
VISUAL CONSPICUITY



MOTION BREAKS CAMOUFLAGE



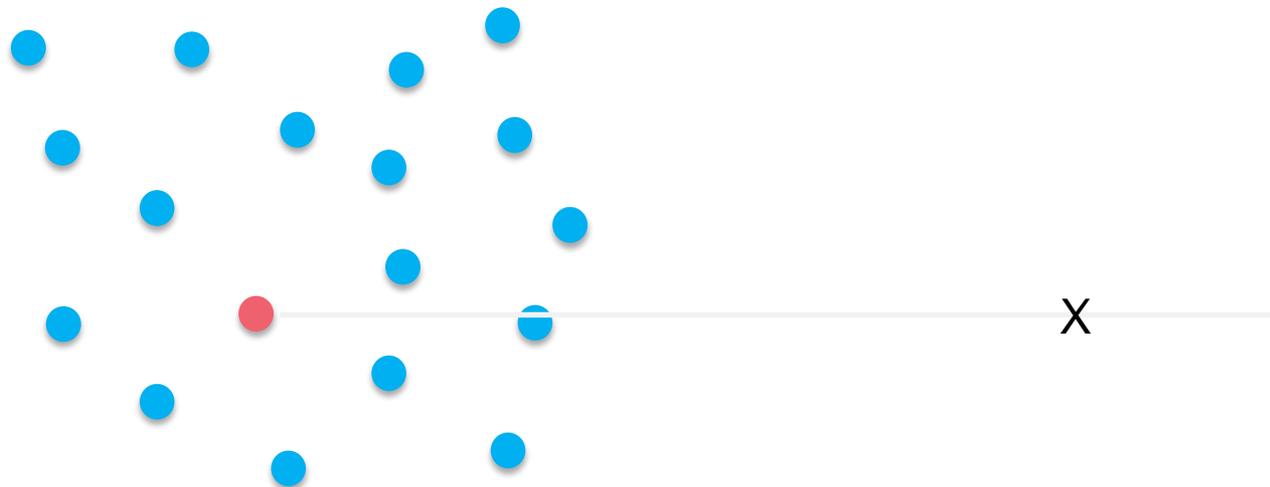
MOTION BREAKS CAMOUFLAGE



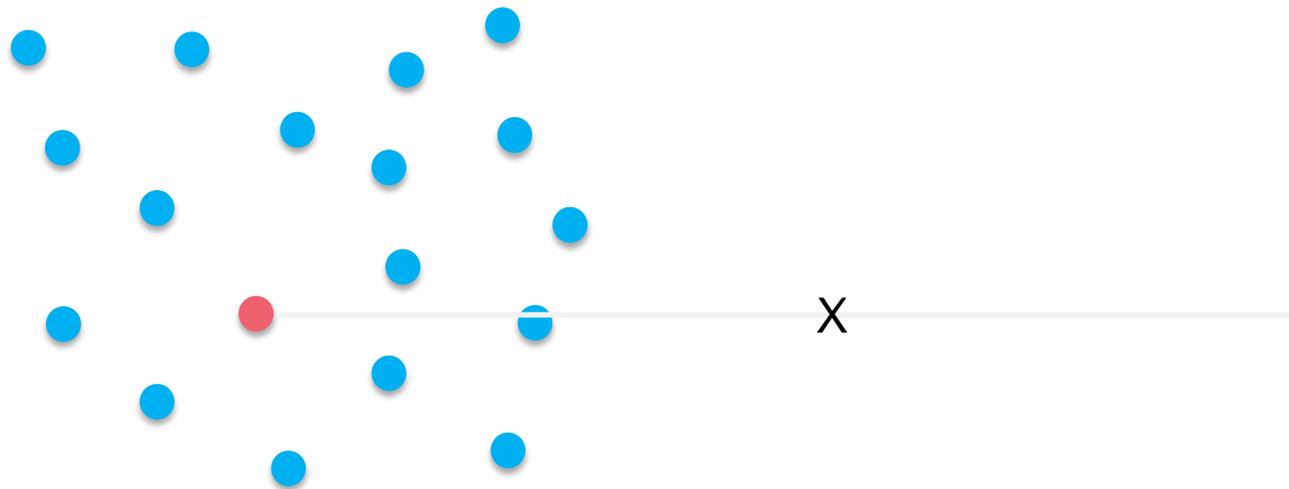
VISUAL CONSPICUITY MEASUREMENT



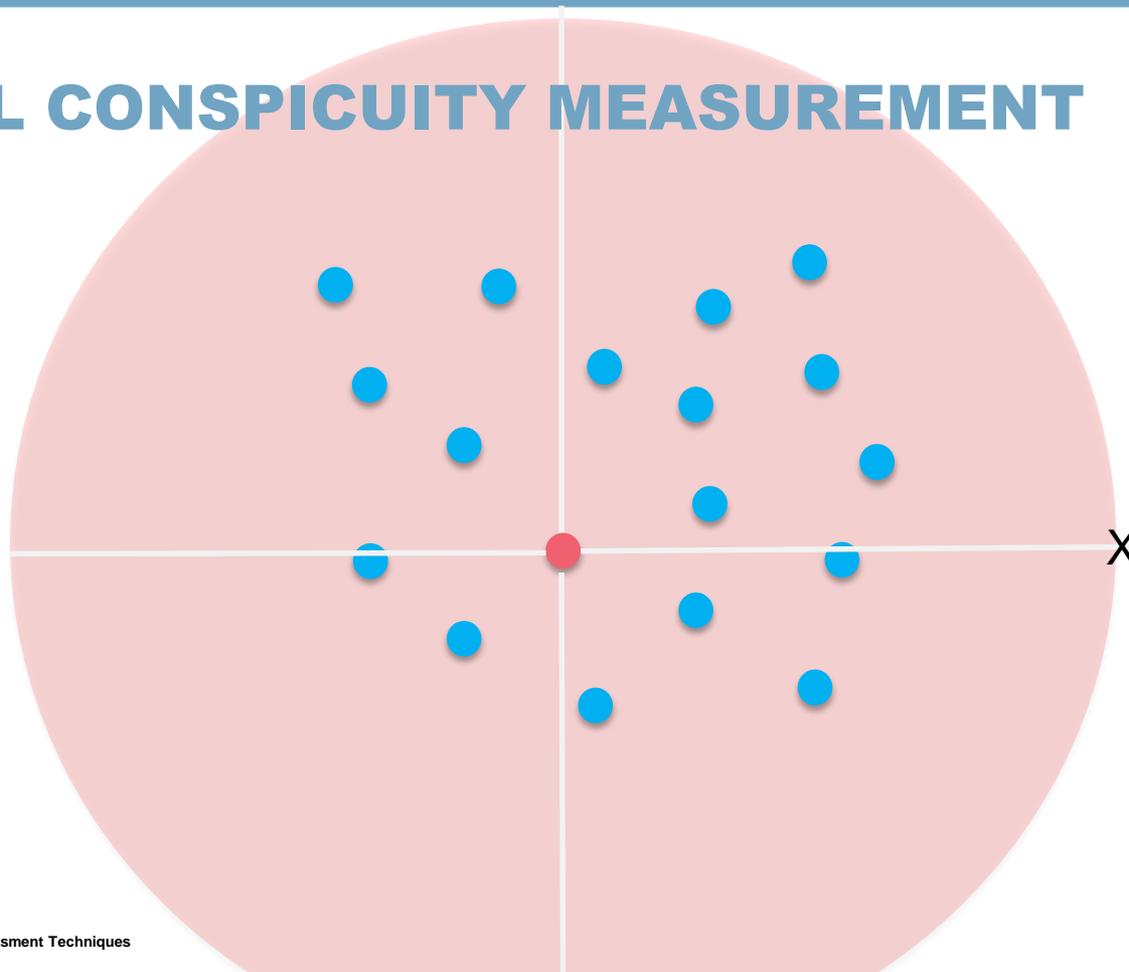
VISUAL CONSPICUITY MEASUREMENT



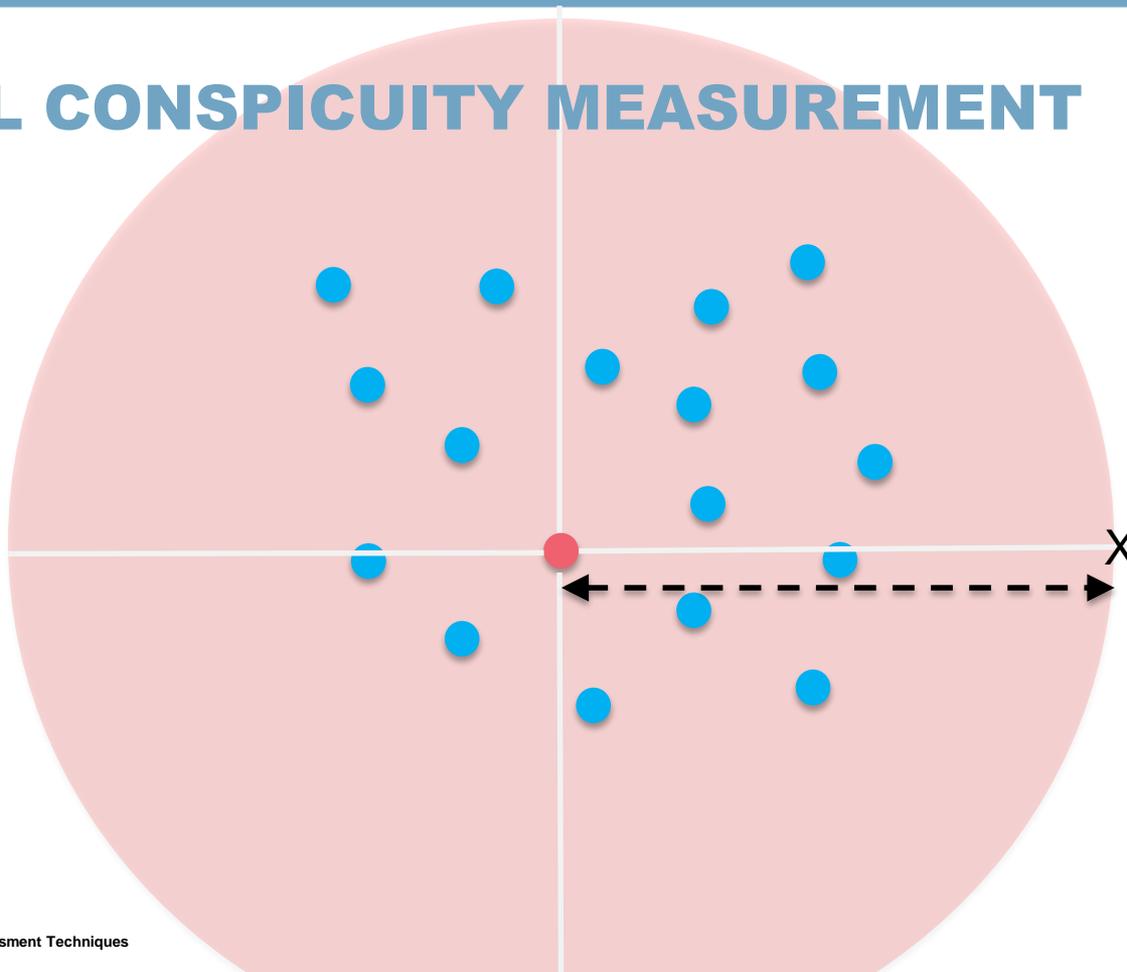
VISUAL CONSPICUITY MEASUREMENT



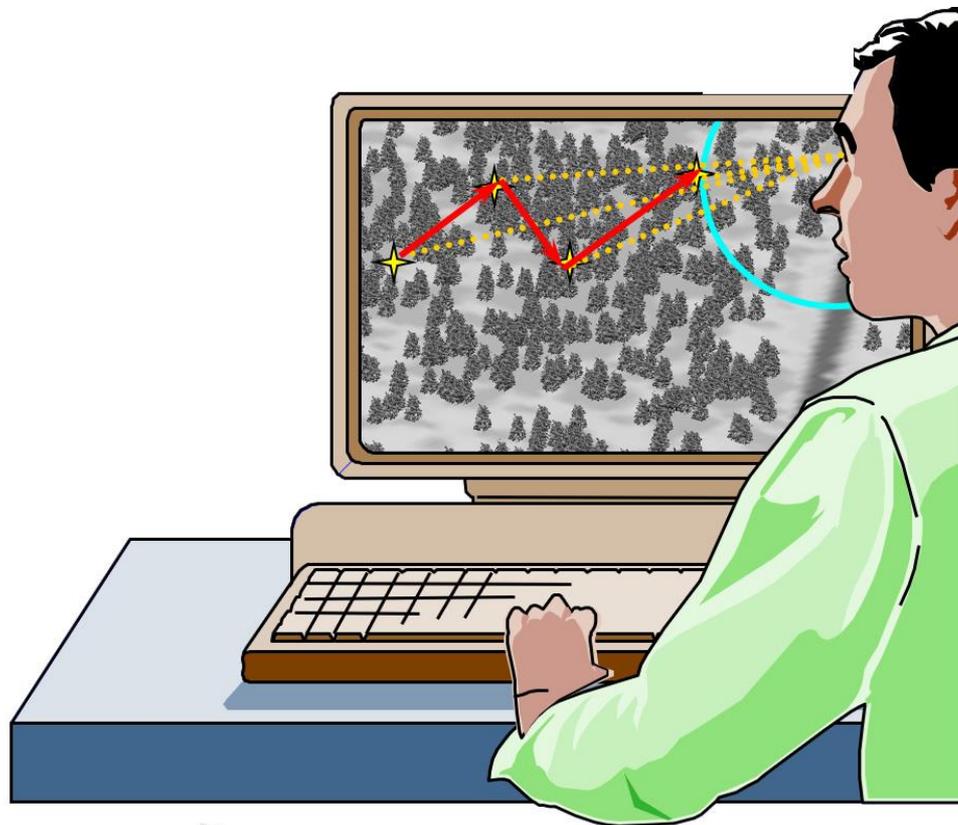
VISUAL CONSPICUITY MEASUREMENT



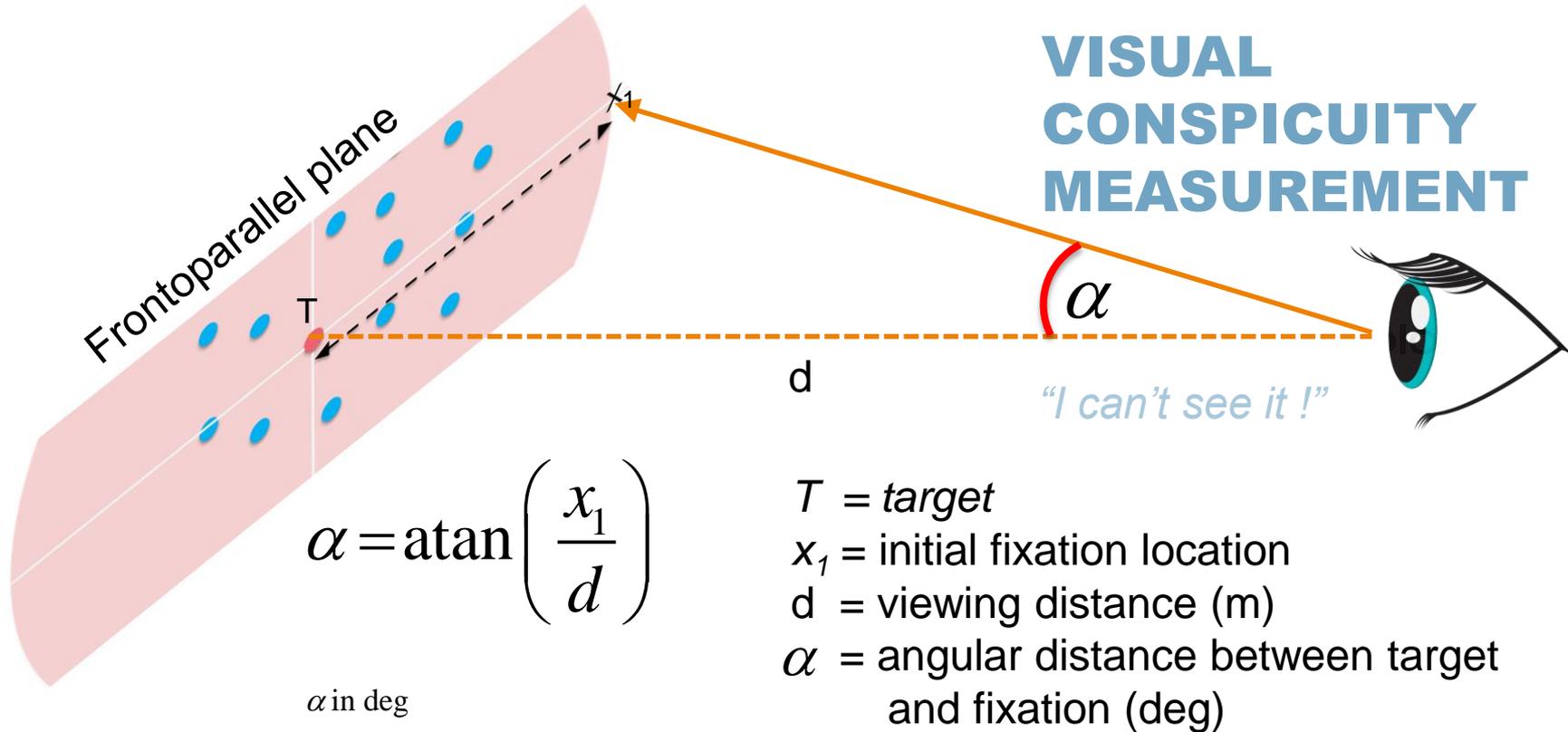
VISUAL CONSPICUITY MEASUREMENT



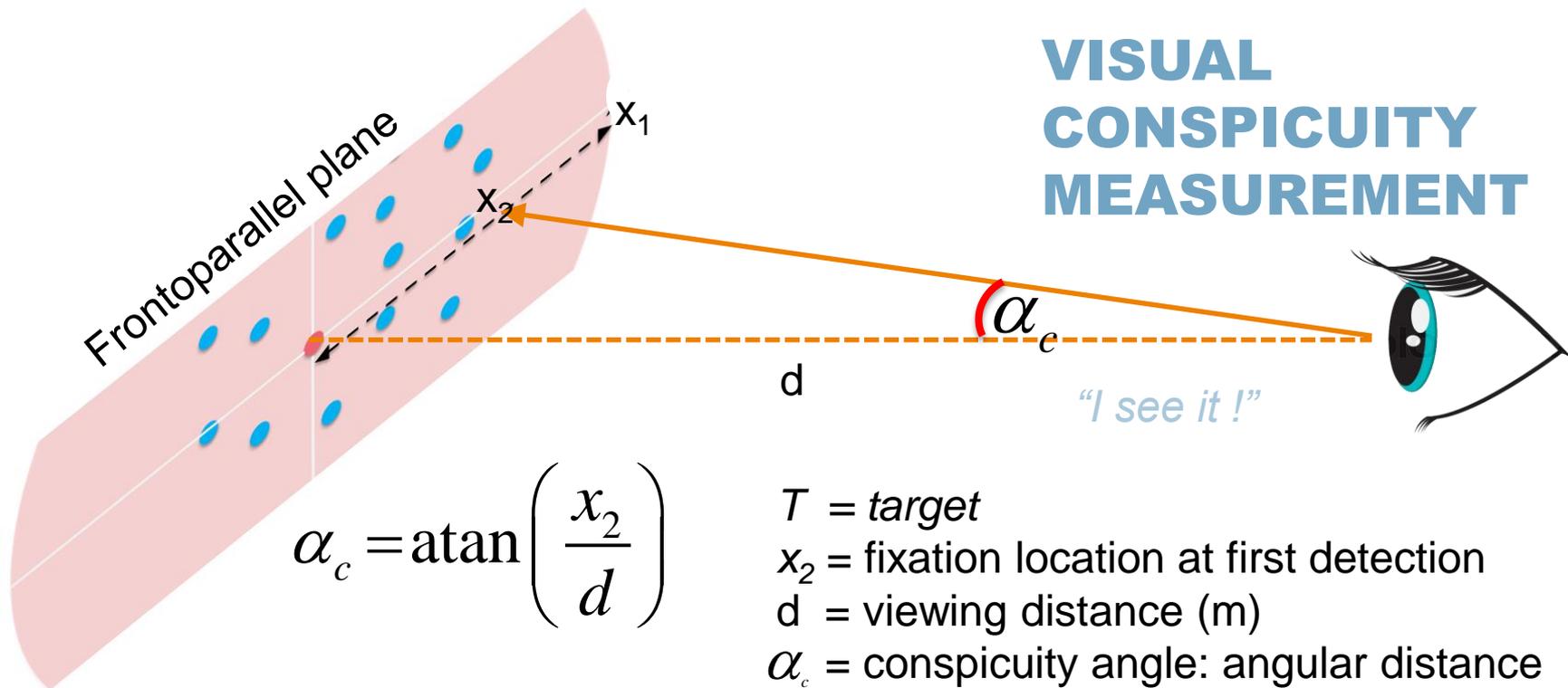
VISUAL CONSPICUITY MEASUREMENT



VISUAL CONSPICUITY MEASUREMENT



VISUAL CONSPICUITY MEASUREMENT



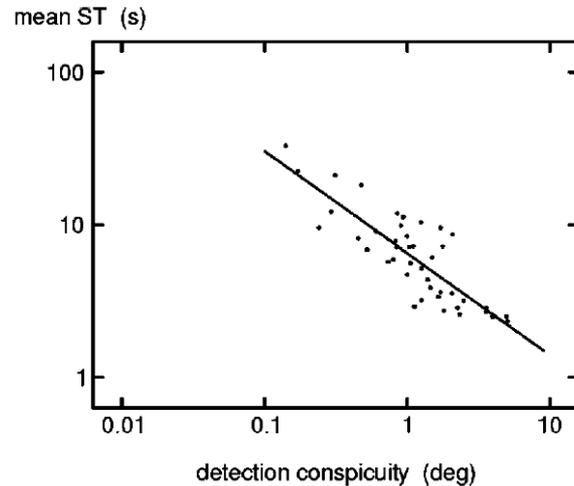
$$\alpha_c = \text{atan} \left(\frac{x_2}{d} \right)$$

α in deg

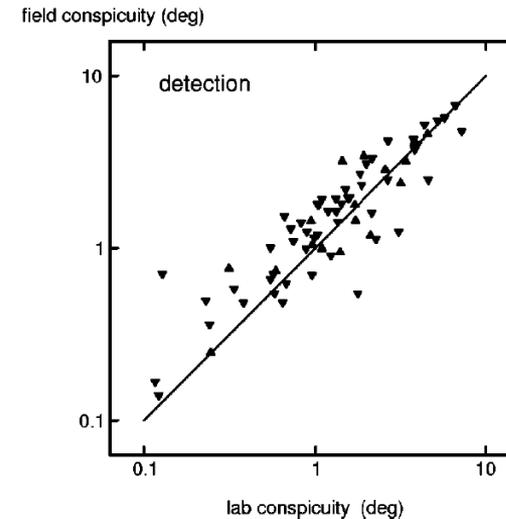
- T = target
- x_2 = fixation location at first detection
- d = viewing distance (m)
- α_c = conspicuity angle: angular distance between target and fixation at first detection (deg)

VISUAL CONSPICUITY MEASUREMENT

Conspicuity determines mean search time



Conspicuity measured in the lab (photosimulation) correlates with conspicuity measured in the field



VISUAL CONSPICUITY MEASUREMENT



Field



Lab



VISUAL CONSPICUITY: SIMULATOR CALIBRATION



(a)

(b)



(c)



(d)



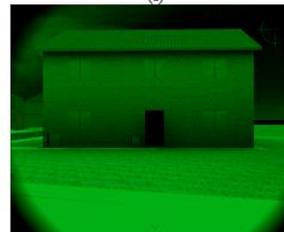
(e)



(f)



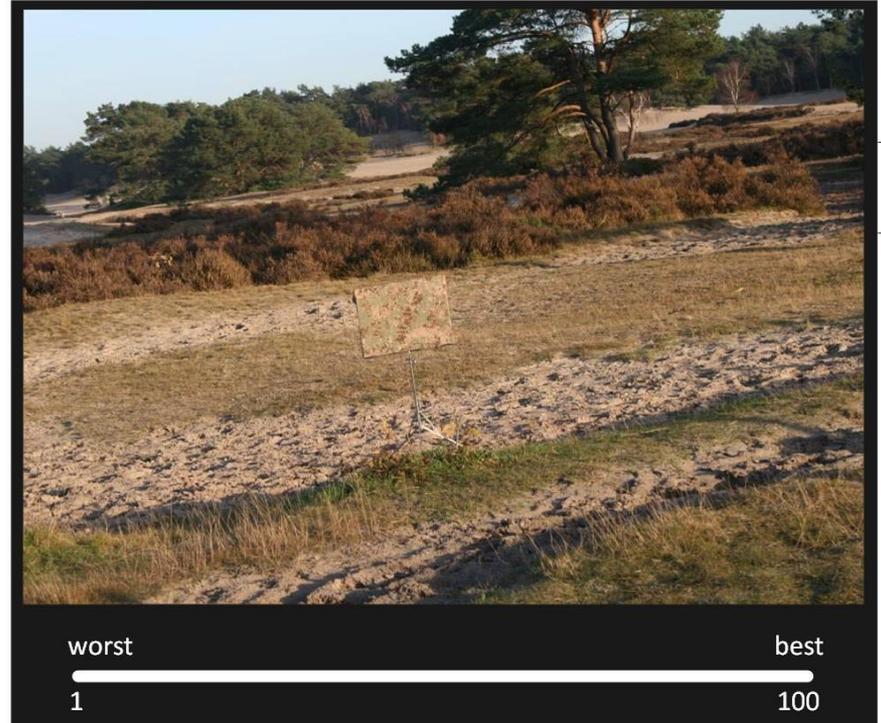
(g)



(h)

PSYCHOPHYSICAL EVALUATION METHODS : SUBJECTIVE BLENDING SCORE

- › Subjective rating how well target matches background
- › Can be done in the field and lab
- › Easy and efficient



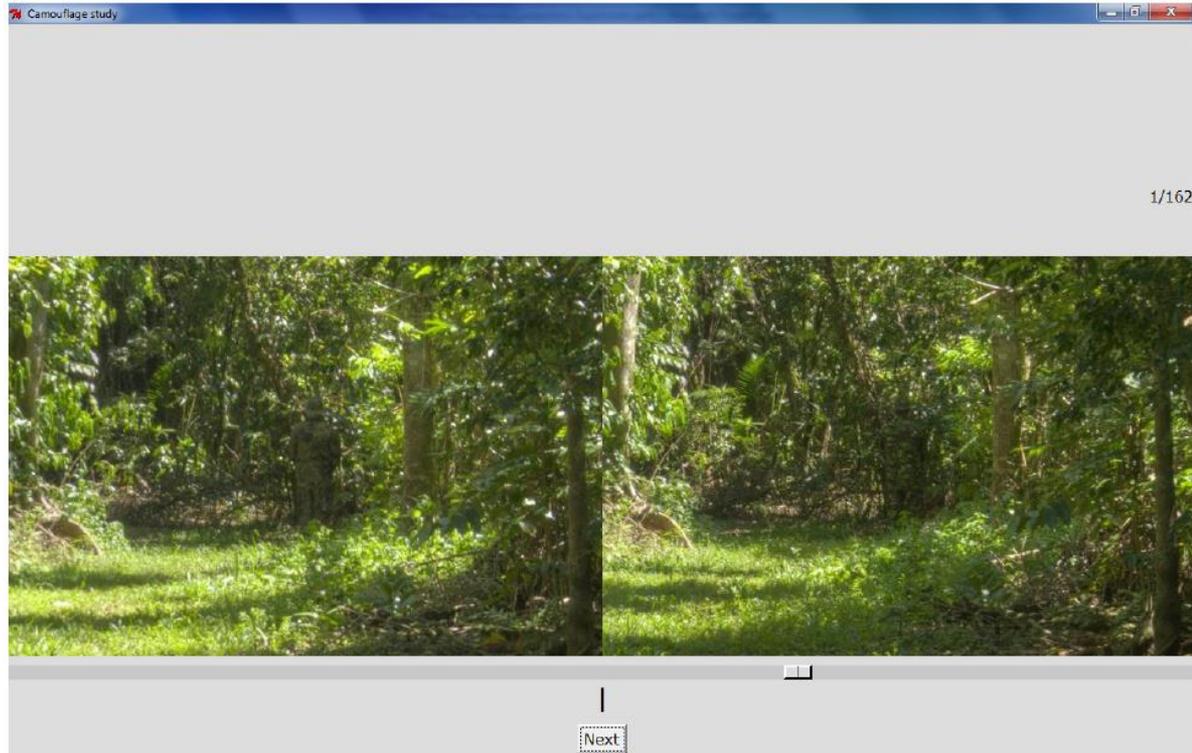
PSYCHOPHYSICAL EVALUATION METHODS : RANKING & PAIRED COMPARISON

- › Ranking targets in printed images from lowest to highest conspicuity



PSYCHOPHYSICAL EVALUATION METHODS : RANKING & PAIRED COMPARISON

- › Paired comparison:
which target is most conspicuous?



PSYCHOPHYSICAL EVALUATION METHODS : RANKING & PAIRED COMPARISON

- › NATO-RTO SCI-219: Camouflage in hot humid areas
- › Overall ranking from lowest to highest conspicuity



PSYCHOPHYSICAL EVALUATION METHODS : **RANKING & PAIRED COMPARISON**

- › NATO-RTO SCI-219: Camouflage in hot humid areas



Figure 7-16: Best (AUS1, Left) and Worst (CAN1, Right) NIR Camouflage Performance at the Challenging High Contrast Scene Sun/Shade Recorded in the Shade on 23.07, with UKs NIR Sensor.

PSYCHOPHYSICAL EVALUATION METHODS : RANKING & PAIRED COMPARISON

- › NATO-RTO SCI-219: Camouflage in hot humid areas



Figure 7-17: Best (CAN1, Left) and Worst (DEU2, Right) LWIR Camouflage Performance Recorded at Night of 23.07, with CAN LWIR Sensor.

PSYCHOPHYSICAL EVALUATION METHODS : EYE TRACKING

› Scanpaths



› Heatmaps



PSYCHOPHYSICAL EVALUATION METHODS : EYE TRACKING

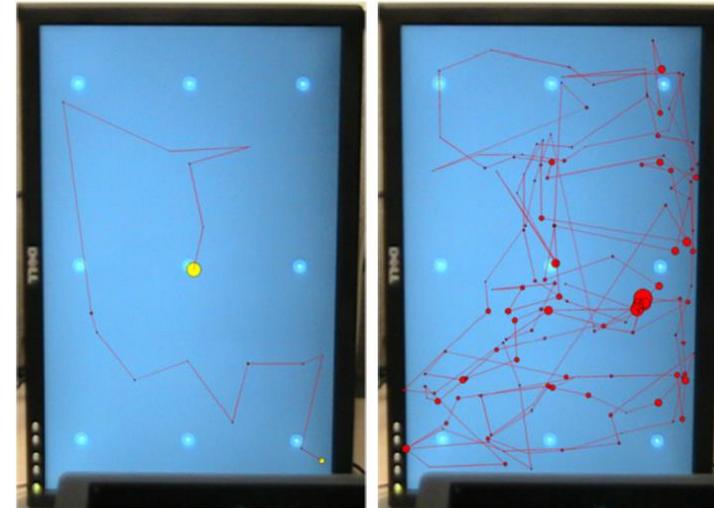
- › Scanpaths
- › Over 120 different performance metrics (Holmqvist & Nystrom, Eye Tracking, Oxford Univ. Press, 2011)
- › Most relevant measures:
 - › Fixation locations
 - › Fixation durations (duration increases with clutter)
 - › Pupil size (pupils dilate with increasing cognitive workload)
 - › Scan path similarity (fixation order, saccadic length)

PSYCHOPHYSICAL EVALUATION METHODS : EYE TRACKING

General findings:

- › Increasing clutter leads to :
 - › Longer fixation times (increasing nr of target-similar features)
 - › Shorter saccades
- › Fixation duration :
 - › Longer for targets than non-targets
 - › Longer for hits than for misses
- › Pupil size :
 - › Larger for targets than for non-targets
 - › Larger for misses than for hits

scanpaths

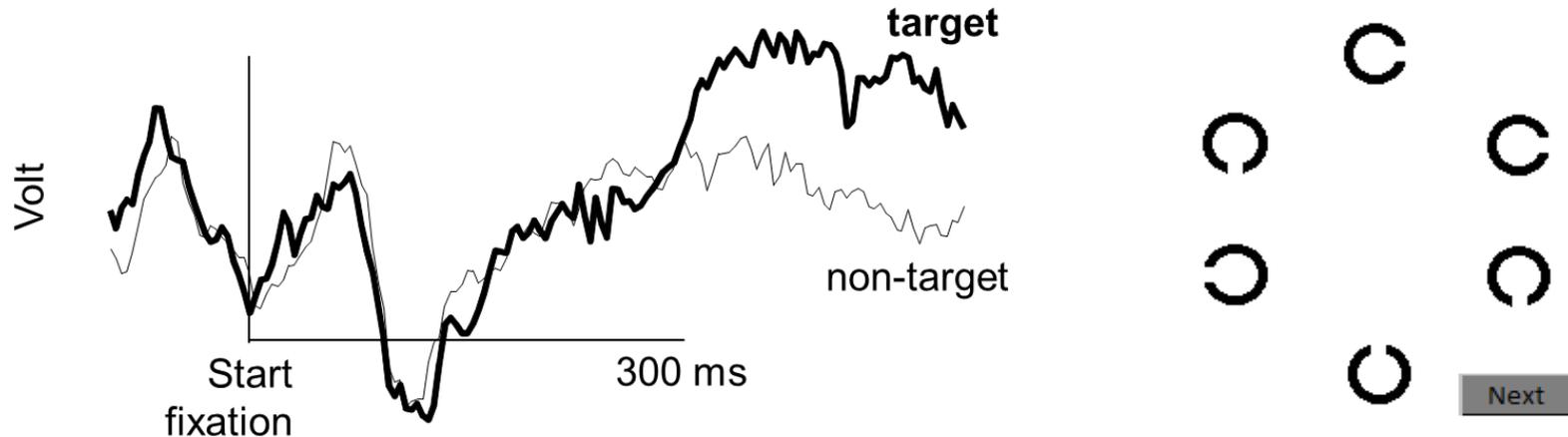


Low clutter

High clutter

PSYCHOPHYSICAL EVALUATION METHODS : FIXATION RELATED ERPS - ATTENTION

- › Distinguishing targets from non-targets: Fixation Event Related Potentials (FRPs)
- › FRPs eliminate the need for subjective (cognitively biased) reports



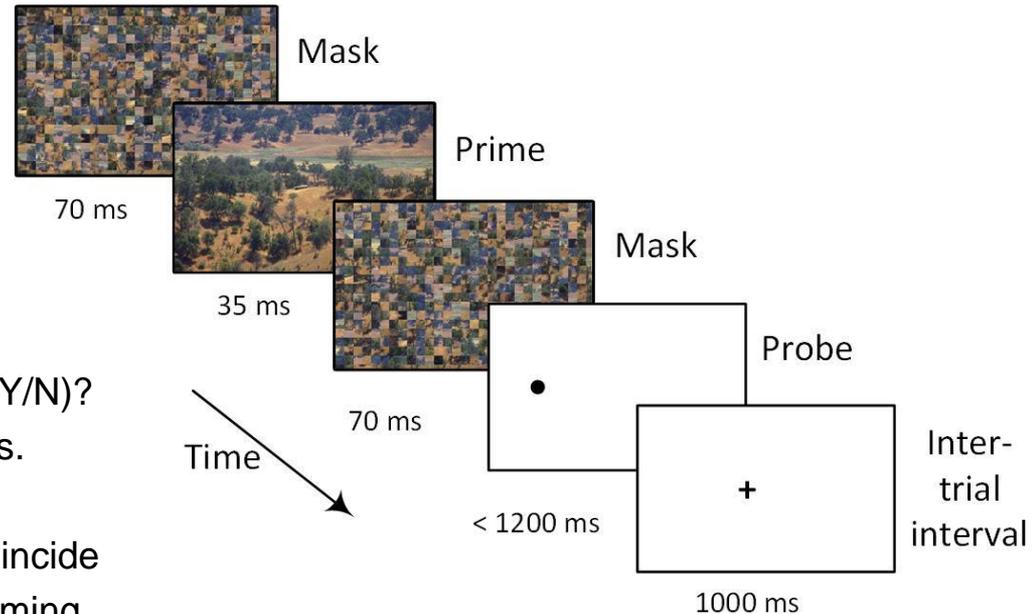
Brouwer, Reuderink, Vincent, van Gerven & van Erp (2013). Distinguishing between target and nontarget fixations in a visual search task using fixation-related potentials. *Journal of Vision*, 13(3):17, 1–10.

Brouwer, Hogervorst, Oudejans, Ries, Touryan (2017) EEG and Eye Tracking Signatures of Target Encoding during Structured Visual Search. *Front. Hum. Neurosci.* 11:264

PSYCHOPHYSICAL EVALUATION METHODS : MASKED PRIMING

- › Procedure :
 - › Forward mask (preceding the prime),
 - › Brief prime (stimulus) presentation,
 - › Backward mask (following the prime),
 - › Dot probe,
 - › Question : target present at dot location (Y/N)?
 - › Measures: error rates and response times.

- › Shorter response time when dot and prime coincide
- › Stimulus presentation time needed to elicit priming effects inversely related to conspicuity

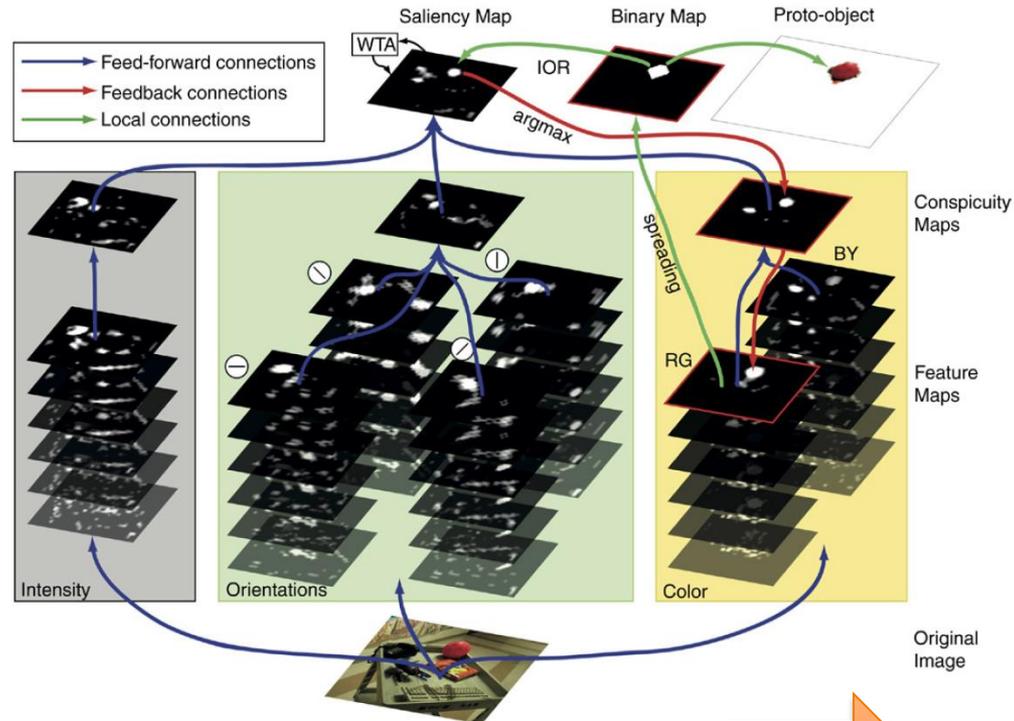


COMPUTATIONAL EVALUATION METHODS : **SALIENCY MODELS**

- › Compute target distinctness relative to background (conspicuity)
- › Accounting for many different features (e.g., color, texture, shape, edge strength, orientation, etc.)

EXAMPLE: SALIENCY TOOLBOX (WALTHER, KOCH, ITTI)

D. Walther, C. Koch / Neural Networks 19 (2006) 1395–1407



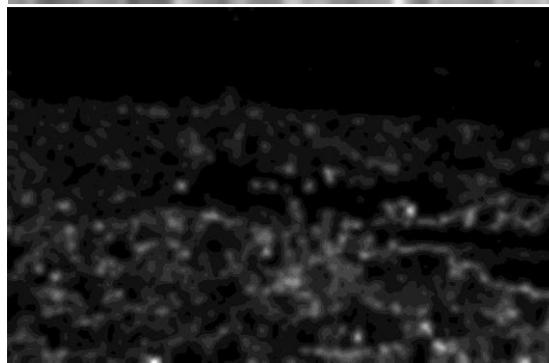
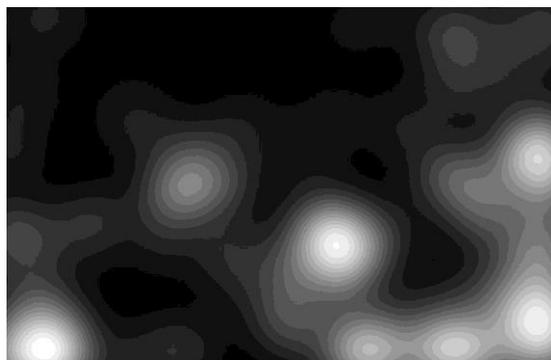
Multiple levels of resolution

Multiple feature maps



COMPUTATIONAL SALIENCY

Different algorithms yield different maps



COMPUTATIONAL SALIENCY



COMPUTATIONAL SALIENCY

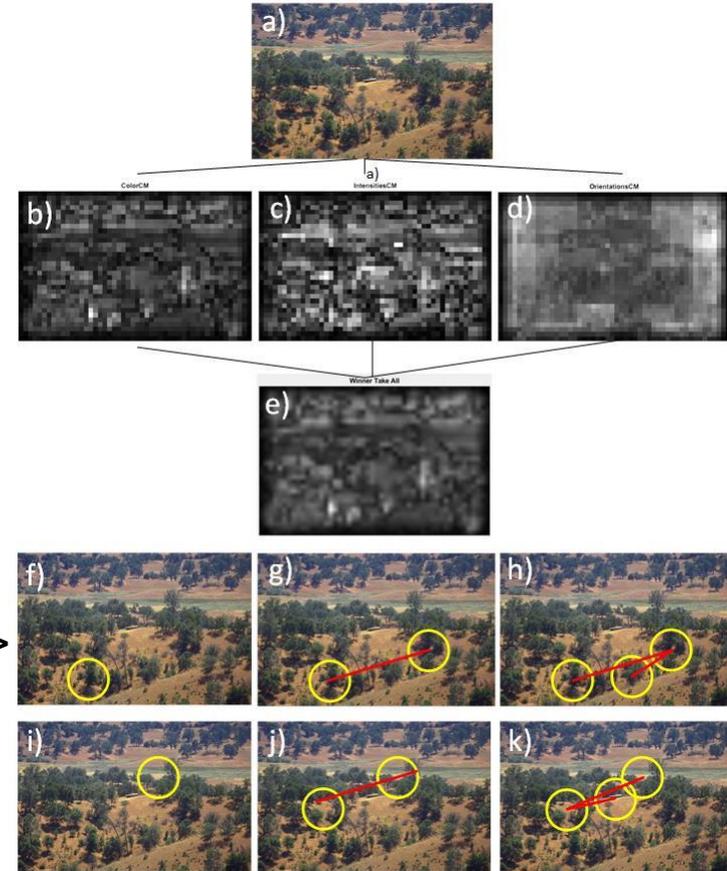


COMPUTATIONAL SALIENCY



FIXATION PREDICTION FROM SALIENCY MAPS

Saliency Toolbox
Walther, Koch & Itti, 2006



Color + intensity + orientation >

intensity (+ orientation) >

SALIENCY BASED SIMULATED FIXATION BEHAVIOR

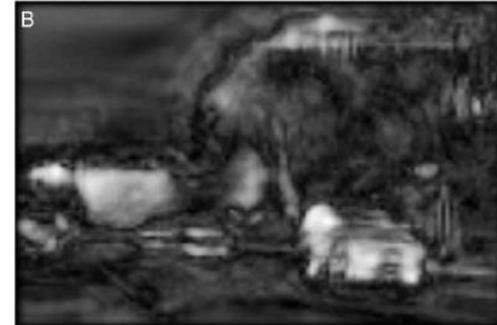
Saliency Toolbox
Walther, Koch & Itti, 2006



SALIENCY BASED SIMULATED FIXATION BEHAVIOR

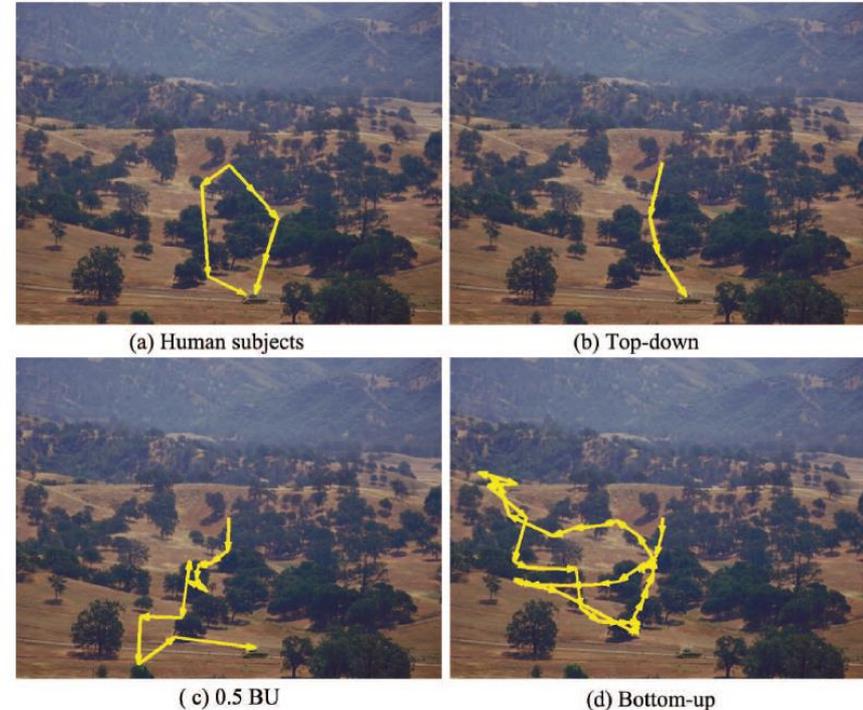
- › Not successful:
 - › Observer scan patterns no correlation with those predicted by (Itti) saliency map models

Foulsham & Underwood, 2008 ;
Underwood, Foulsham & Humphrey, 2009

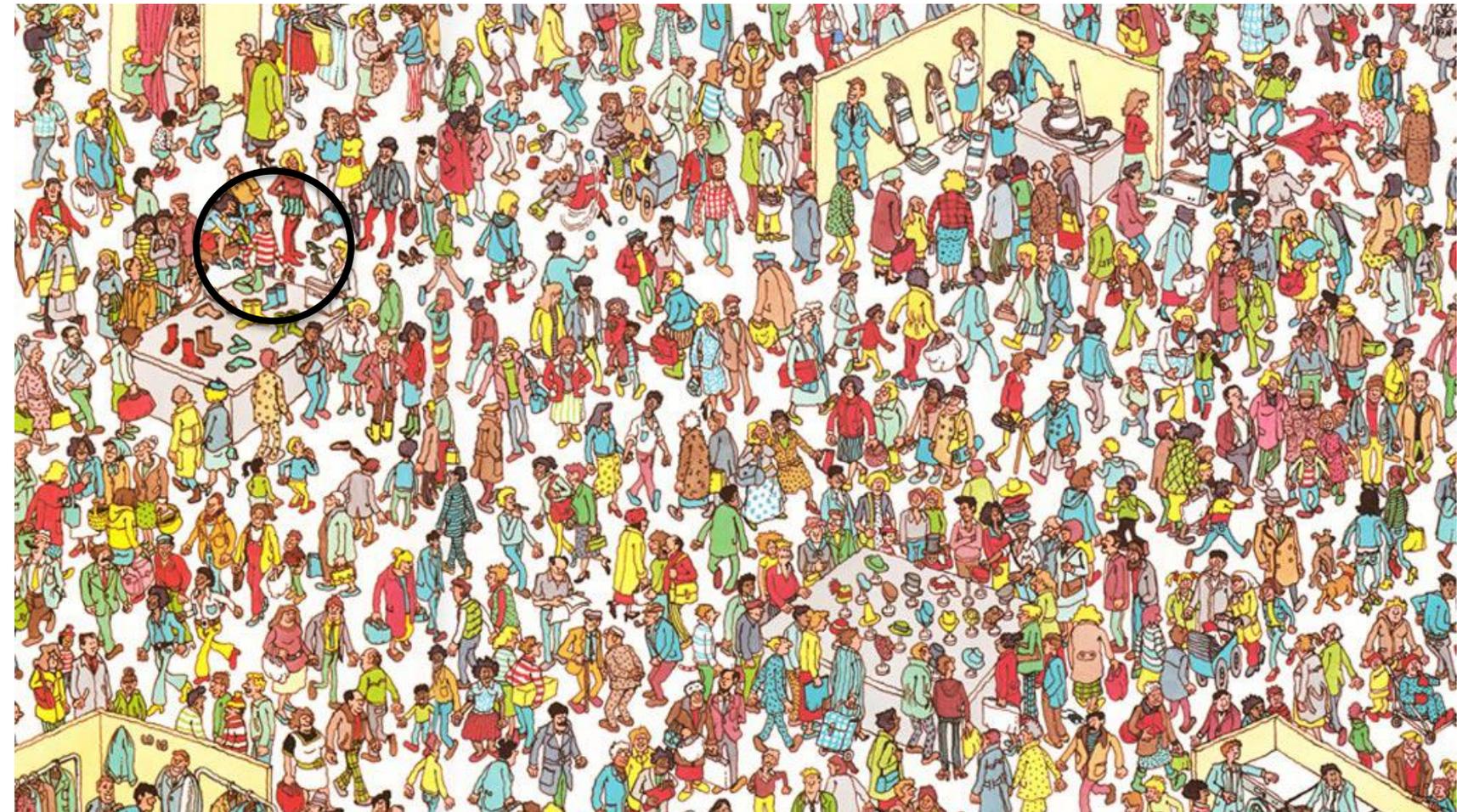


BOTTOM-UP VS TOP-DOWN SALIENCY

- › Bottom-Up (BU) saliency: regular CS filters
- › Top-down (TD) saliency: correlation of BU saliency map with target template filter
- › TD map predicts human fixation behaviour better than bottom-up (BU)



CLUTTER AND TARGET SIGNATURE METRICS



Where's
Waldo?



COMPUTATIONAL EVALUATION METHODS : CLUTTER AND TARGET SIGNATURE METRICS

- › Static targets:
 - › Edge detection
 - › Texture metrics (e.g. CAMAELEON)
 - › Contrast energy detection
- › Dynamic targets
 - › Correlation
 - › Gradient
 - › Energy



COMPUTATIONAL EVALUATION METHODS : CLUTTER AND TARGET SIGNATURE METRICS



› CAMAELEON

- › Target-background contrast in terms of
 - › local energy
 - › local spatial frequency
 - › local orientation



COMPUTATIONAL EVALUATION METHODS : SEARCH MODELS

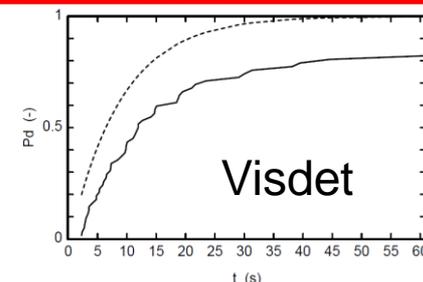
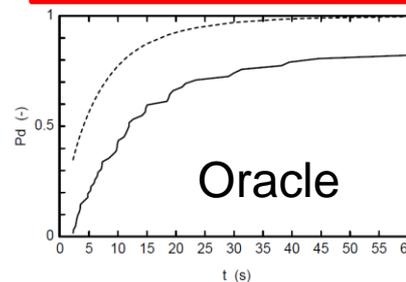
FOR

› Input parameters e.g. :

- › Luminance:
 - › target
 - › local background
 - › overall scene
- › Dimensions:
 - › target
 - › FOV
 - › FOR

› Output:

- › Mean search time
- › $P_d(t)$

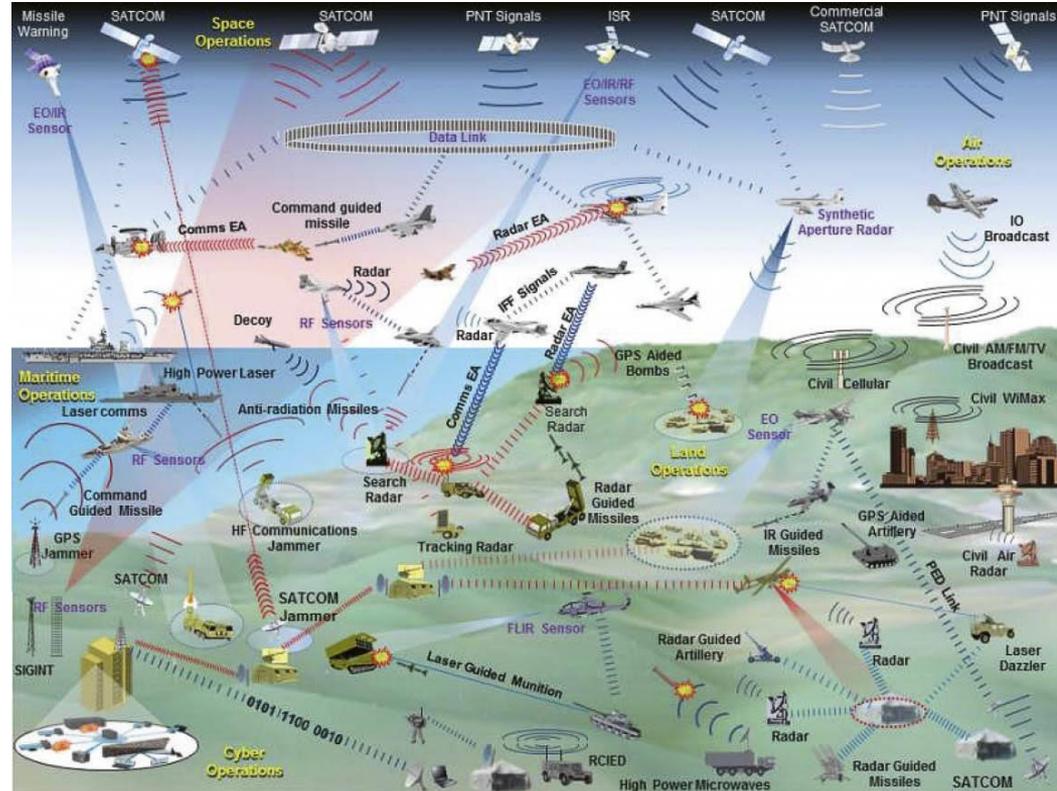


FUTURE CHALLENGES

- › Camouflage
 - › can one hide on the modern battlefield?

or

- › Deception
 - › can we spoof modern sensors?



ACTIVE CAMOUFLAGE

- › Yehudi lights:
lamps of automatically-controlled brightness placed on the front and leading edges of an aircraft to raise its luminance to the average sky brightness

Developed by US Navy from 1943 onwards.

Increased interest due to stealth technology.



ACTIVE CAMOUFLAGE

- › Yehudi lights:
 - lamps of automatically-controlled brightness placed on the front and leading edges of an aircraft to raise its luminance to the average sky brightness

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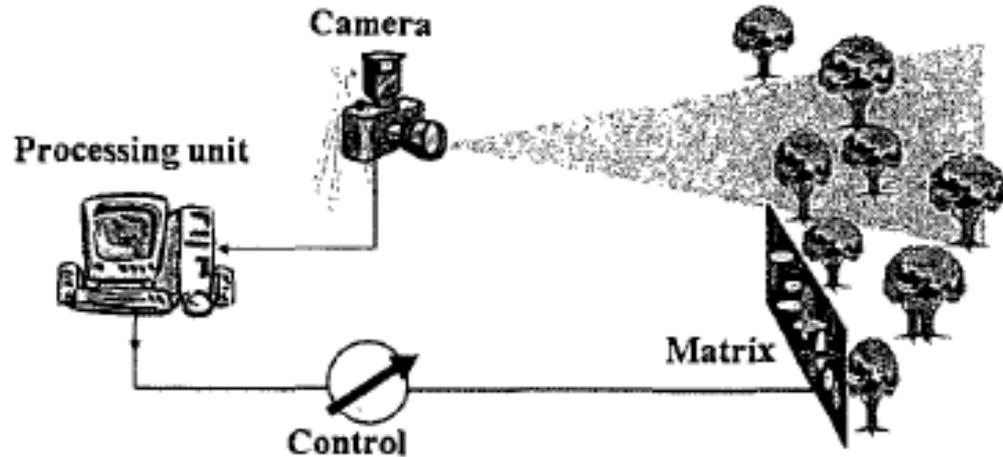
Increased interest due to stealth technology.



ACTIVE CAMOUFLAGE

› Adaptive camouflage: CAMELEON (TNO, Holst, CA, GE)

Green	Control VIS	Fixed emission	Control emission	Brown
Control emission	Fixed emission	Black	Fixed emission	Control VIS
.....



ACTIVE CAMOUFLAGE

› CAMELEON (TNO, Holst, CA, GE)

<https://www.youtube.com/watch?v=zLdNeatXCvE>

or Google on:

“Toet Cameleon Youtube”



ACTIVE CAMOUFLAGE

› CAMELEON (TNO, Holst, CA, GE)

<https://www.youtube.com/watch?v=zLdNeatXCvE>

or Google on:

“Toet Cameleon Youtube”



ACTIVE CAMOUFLAGE: BAE ADAPTIVE SYSTEM

ADAPTIV PREVENTS IR DETECTION OF
LAND BASED VEHICLES



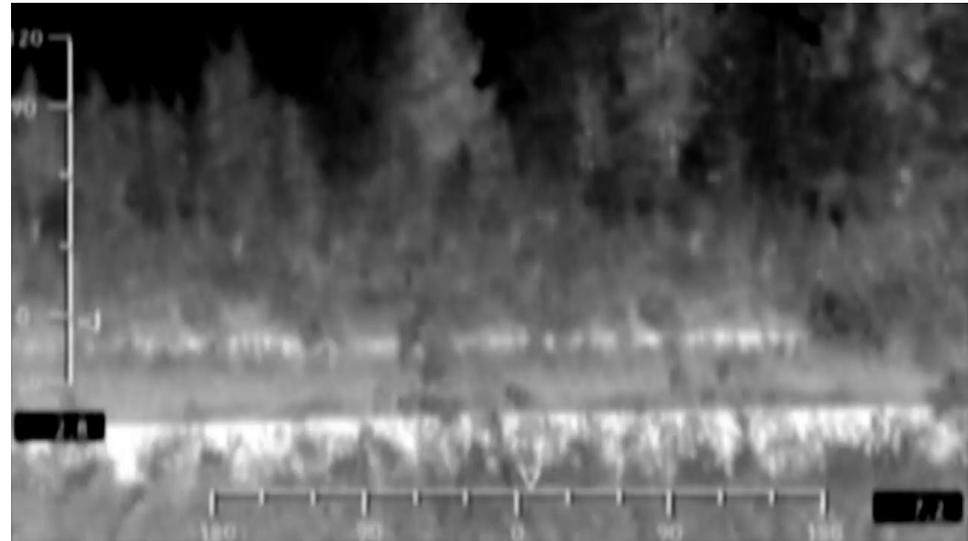
Peltier elements



ACTIVE CAMOUFLAGE: BAE ADAPTIVE SYSTEM



system inactive



system activated

ACTIVE CAMOUFLAGE: BAE ADAPTIVE SYSTEM

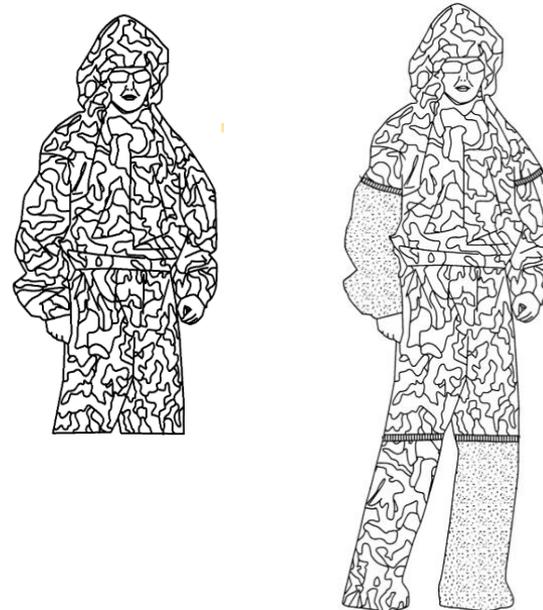


ACTIVE CAMOUFLAGE: BAE ADAPTIVE SYSTEM



MULTISPECTRAL CAMOUFLAGE

- › A multispectral image is typically a 4-6 band image: RGB + one or more infrared bands
 - › Camouflage through multilayered textiles with
 - › different reflection and absorption characteristics
 - › different patterns
- in each of the spectral bands



ACTIVE MULTISPECTRAL CAMOUFLAGE

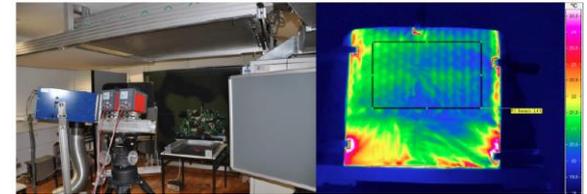
- › Adaptive Camouflage for the Soldier II (ACAMSII)
 - › Project in EU PADR program
 - › SE, DE, PT, LT, NL, FR
 - › Start: May 1, 2018
 - › End: April 30, 2021
 - › 2.6 M€



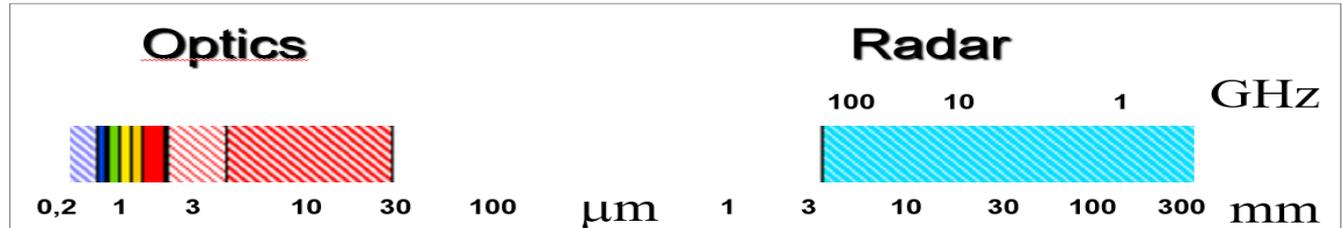
ACTIVE MULTISPECTRAL CAMOUFLAGE

Adaptive Camouflage for the Soldier II (ACAMSII)

- research on novel materials and components



- Multispectral camouflage: Visual, NIR, SWIR, MWIR, LWIR, Radar



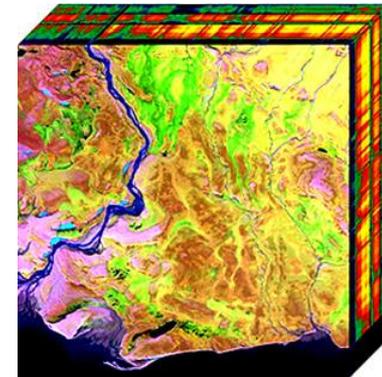
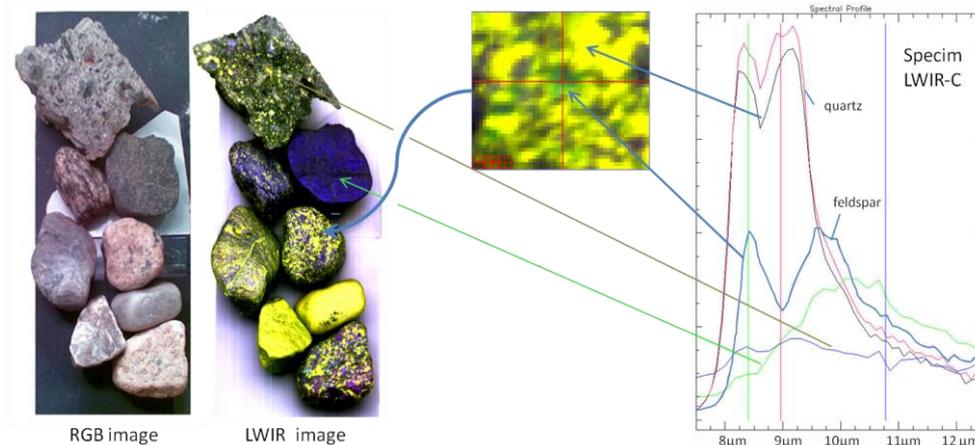
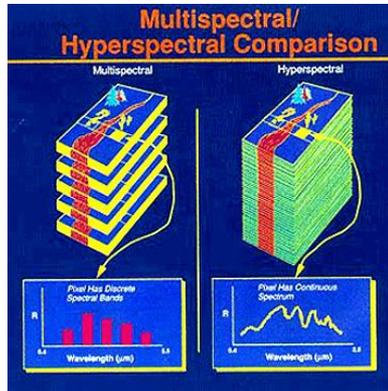
ACTIVE CAMOUFLAGE

Ultimate goal: the invisible soldier



HYPERSENSPECTRAL CAMOUFLAGE

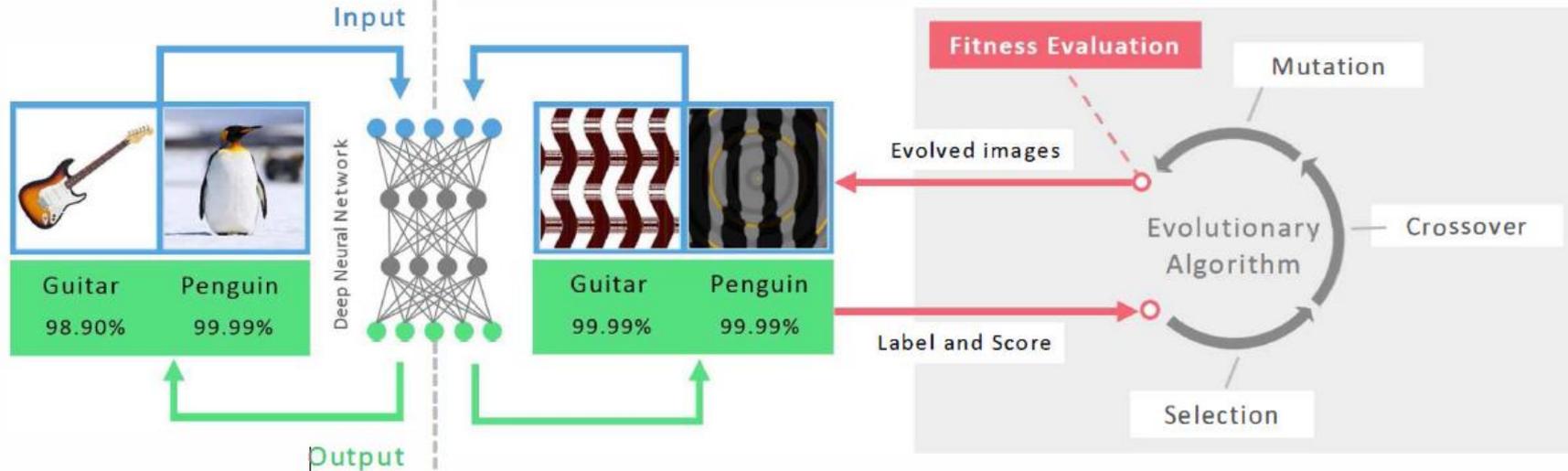
- › A hyperspectral image typically has ~200 bands, each band representing the response to a precise wavelength of light.
 - › A representative (200 D) signal for a material is called a hyperspectral signature.
 - › We can form these signatures into a spectral library for classification.



FOOLING AUTOMATIC DETECTION SYSTEMS

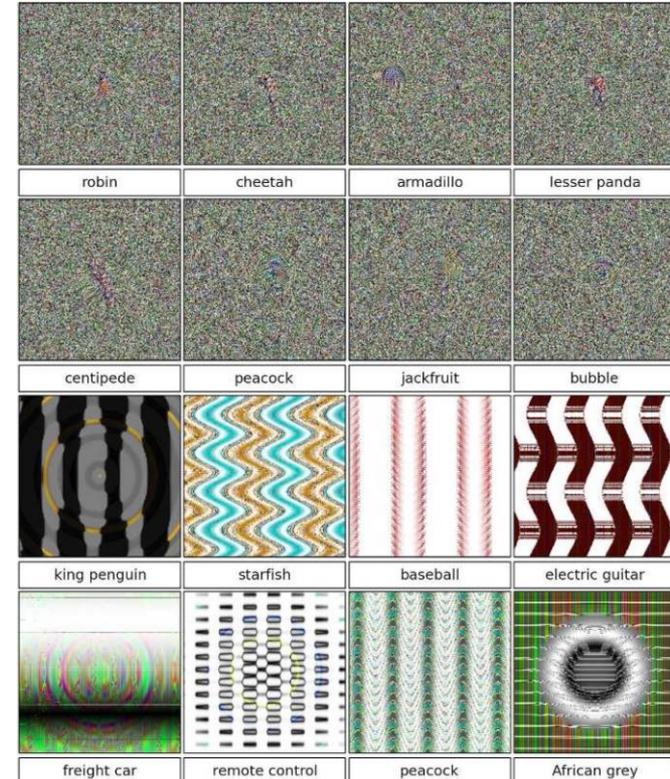
1 State-of-the-art DNNs can recognize real images with high confidence

2 But DNNs are also easily fooled: images can be produced that are unrecognizable to humans, but DNNs believe with 99.99% certainty are natural objects



FOOLING RECOGNITION SYSTEMS

- › it is easy to produce images that are completely unrecognizable by humans
- › but that state-of-the-art DNNs believe to be familiar objects with 99.99% confidence



FOOLING AUTOMATIC DETECTION SYSTEMS

- › Automatic person detection systems can easily be fooled



FOOLING RECOGNITION SYSTEMS

- › Automatic face recognition systems can easily be fooled



- › So WWI camouflage may become fashionable again



1917: A soldier in World War I models early camouflage. (Courtesy: National Archives/Department of Defense)

A wide-angle photograph of a lush green field filled with numerous small yellow wildflowers. In the background, a dense forest of various green trees stretches across the horizon under a clear blue sky. The text 'Thank you for your attention!' is overlaid on the image in a large, bold, sans-serif font. The letters of the text are filled with a brown and tan camouflage pattern and have a thin orange outline.

Thank you
for
your attention !