

Workshop 4

# Robotisering en de gevolgen voor fysieke belasting

*Door: Michiel de Looze en Reinier Könemann (TNO) en Marcel Grooten (TOM Projects & Interim)*

Bijeenkomst duurzaam fysiek werk  
Leren en innoveren

**op weg naar duurzame inzetbaarheid**




Tools & Toys

Jobs & Joys



## World Wide

**IFR International Federation of Robotics**



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**ISO** Online Browsing Platform (OBP)

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**SPARC** The Partnership for Robotics in Europe

ISO 8373:2012(en) Robots and robotic devices — Vocabulary

## The Netherlands

**ROBONED**

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**TU Delft**

TU DELFT ROBOTICS INSTITUTE NEWS DELFTROBOTICS

Info & Actuality intelligence at work

**UNIVERSITEIT TWENTE**

RAM Robotics and Mechatronics

HOME WELCOME TO ROBOTICS AND MECHATRONICS

**LEO** CENTER FOR SERVICE ROBOTICS

**TU/e** Technische Universiteit Eindhoven University of Technology

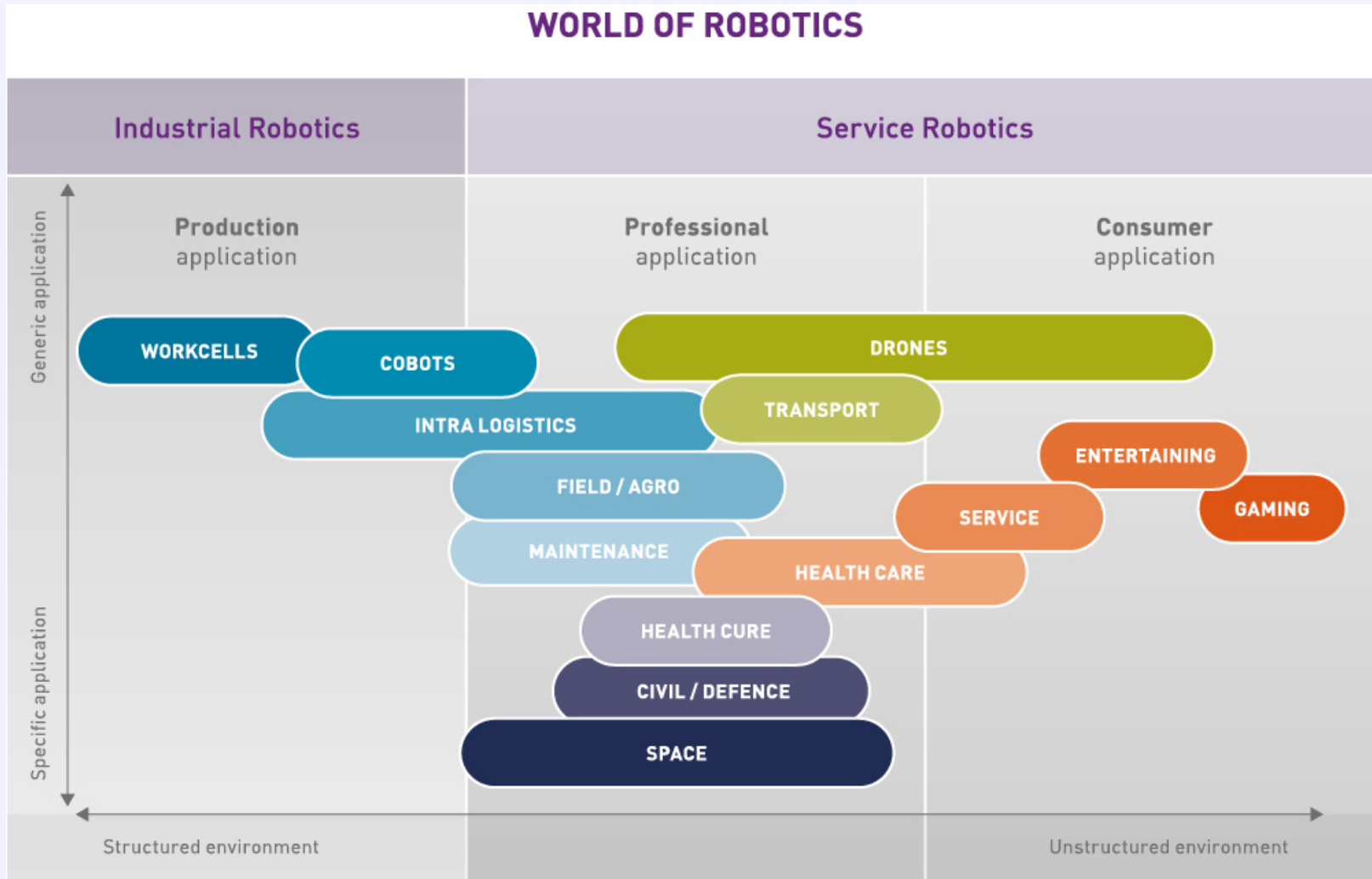
Education Research Innovation University

HOME PROJECTS MEMBERS

Robotics Research

General Projects Research groups Cooperation

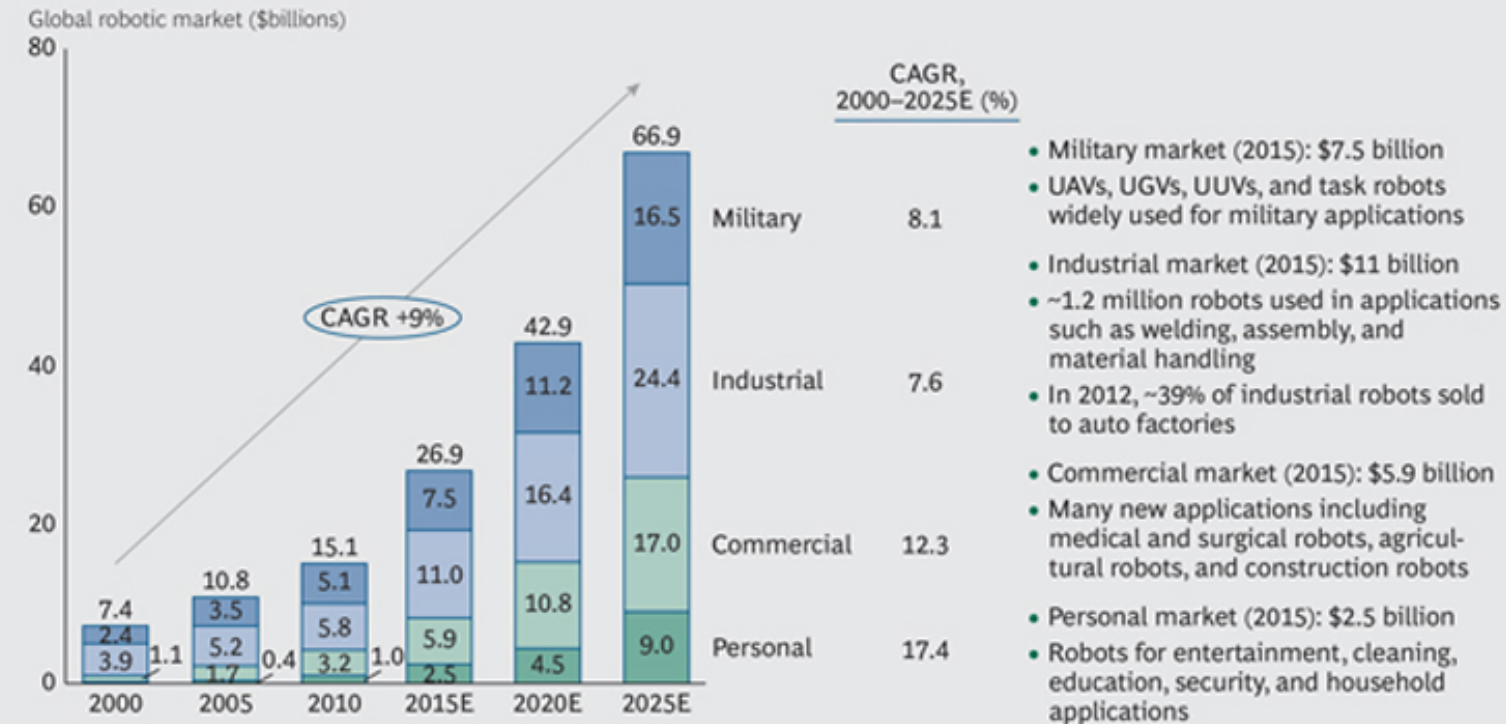
**ROBOTS.NU** Robotmerken Robotcategorie Robotnieuws Robotshop





# World Market Growth

**EXHIBIT 1 | Worldwide Spending on Robotics Is Expected to Reach \$67 Billion by 2025**



**Sources:** International Federation of Robotics, Japan Robot Association; Japan Ministry of Economy, Trade & Industry; euRobotics; company filings; BCG analysis.  
**Note:** UAV = unmanned aerial vehicle; UGV = unmanned ground vehicle; UUV = unmanned underwater vehicle. Estimates do not include the cost of engineering, maintenance, training, or peripherals.

Source: Boston Consulting Group 2014



## Characteristics

- Around for over 40 years
- Types & sizes 6DOF / SCARA / DELTA
- 75% of the market Big 4 (AFKY)  
*e.g. Yaskawa* 24.000 units/yr
- Average price HW \$ 50K/unit
- Minimum pricing \$ 20K (SCARA)
- Robot density NL low 93 robots/10K FTE
- Market Benelux 1900 units/yr;
- NL about 800 units/yr

*Data irf.org*

## Trends

- Focus on **TCO** and **Productivity**  
*Payload, Accuracy, Speed and Reliability*
- Enhanced SW and control
- Random Order Picking
- Mobile robots on AGV
- Automated warehouse & logistics
- Automated work cells



And many others  
whereas:

Adept, Cloos, Comau, Epson,  
Denso, Hyundai, Kawasaki,  
Mitsubishi, Nachi, Electric,  
Panasonic, Reis, Schunk,  
Staubli, Toshiba, Yamaha,

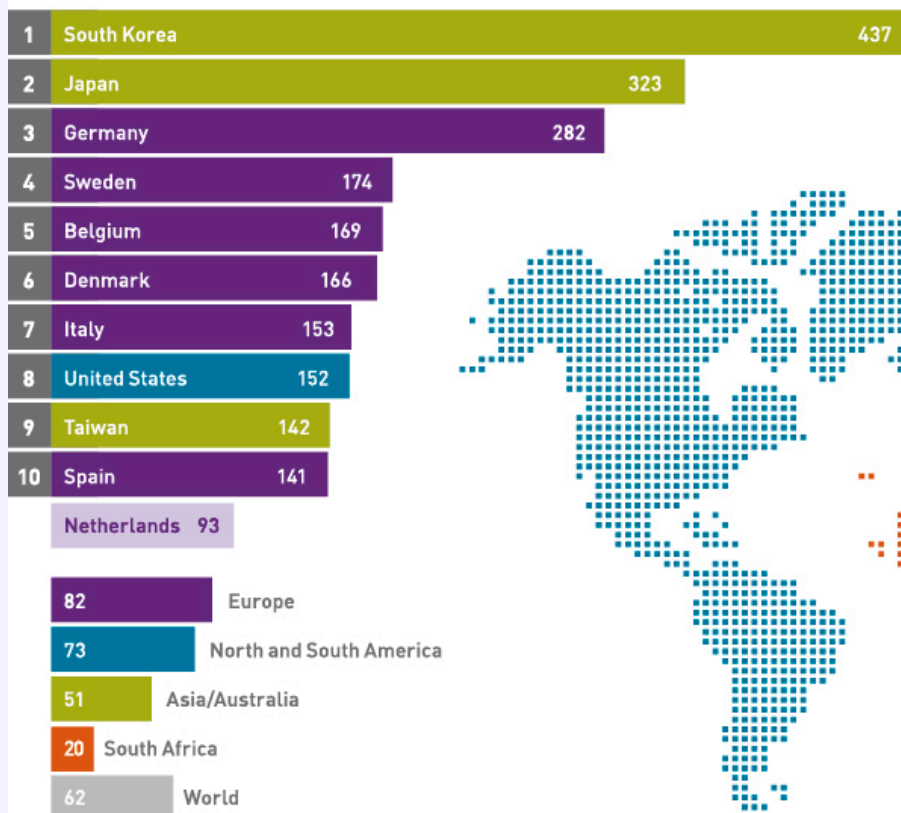
Foremost Japanese and German  
Billion dollar companies....



# Color Branding



## TOP10 COUNTRIES OF ROBOT DENSITY



Source: IFR World Robotics 2014; Robot density per 10.000 operators in production



## Drivers

- Automate **Dull, Dirty, Dangerous** applications
- Industry 4.0 / Smart Industry
- Human – Machine Collaboration
- Flexibility due to decline Product Life Cycle
- New and affordable HW/SW technology & materials

## China/Asia growing 40%



新闻资讯 [ 新松公司北方区域总部落户青岛 | 2014/7/25 ] [ 公司新闻 | 行业新闻 | 媒体关注 ]

 <p><b>工业机器人</b> 30年技术积累 12年工程应用</p>	 <p><b>并联机器人</b> 高性能 高效率 高性价比</p>	 <p><b>AGV自动导引车</b> 民族品牌 国际品质</p>
 <p><b>智能仓储物流</b> 物流设备顶级供应商</p>	 <p><b>自动化成套设备</b> 研发与应用的权威机构</p>	 <p><b>煤焦化制样机</b> 全自动化操作 提升企业形象</p>

## China's Industrial Robot Boom Amazes Experts

Robots prime acquisition as China's new factories arise

By Tom Green



**ProB – ROBERTA – SPEEDY-10 – BAXTER**  
**ABB YUMI – KUKA IIWA – UNIVERSAL ROBOTS**  
**PF 400 – NEXTAGE – APAS – BIOROB**



New in industry, especially for SME:

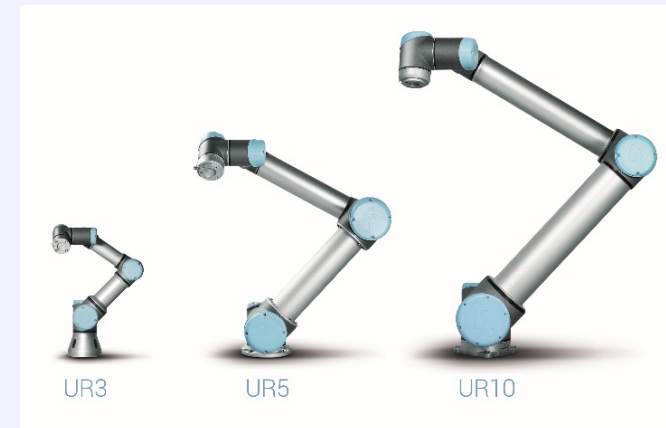
- Low cost
- Easy and fast programmable
- Safe operation

*PART4You Audi*



## Universal Robotics, Denmark

- 2005 Started company
- 2009 Product on the market
- 2014 Sold 4.000 units total,  
Revenue \$100M
- 2015 new UR3
- Target sales 4.000 pc
- 2017 Target Revenue \$200M



## Rethink Robotics, USA

- Baxter
- Sawyer (new 2015)
- Strong investments and marketing



## Universal Robots



## Basic Principles

- Move Robot to work location, not work to robot cell
- Small footprint.  
Fit within existing shop-floor layout
- Programming/teaching by operator

## Van Wees Waalwijk Mobiële robot

De mobiele robot is een door Van Wees Waalwijk ontwikkeld concept. Deze robot kan gezien worden als een flexibele werknemer, aangezien hij op meerdere plekken inzetbaar is, eenvoudig te programmeren is en er geen hekwerk voor vereist is. Door deze multifunctionaliteit kan hij optimaal benut worden en wordt de 'return on investment' sterk vergroot!

- [Terug naar overzicht](#)





- Tele-operation
- Micro surgery
- Minimal invasive
- Endoscopy

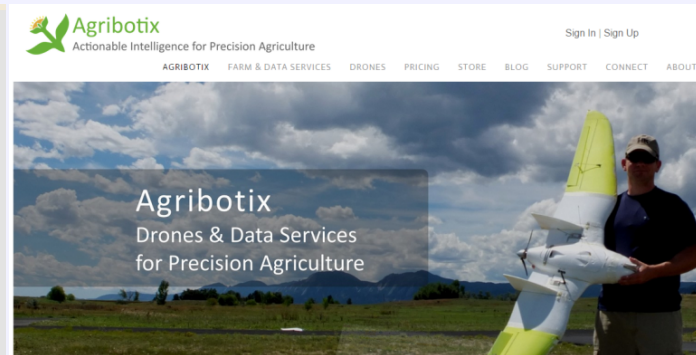
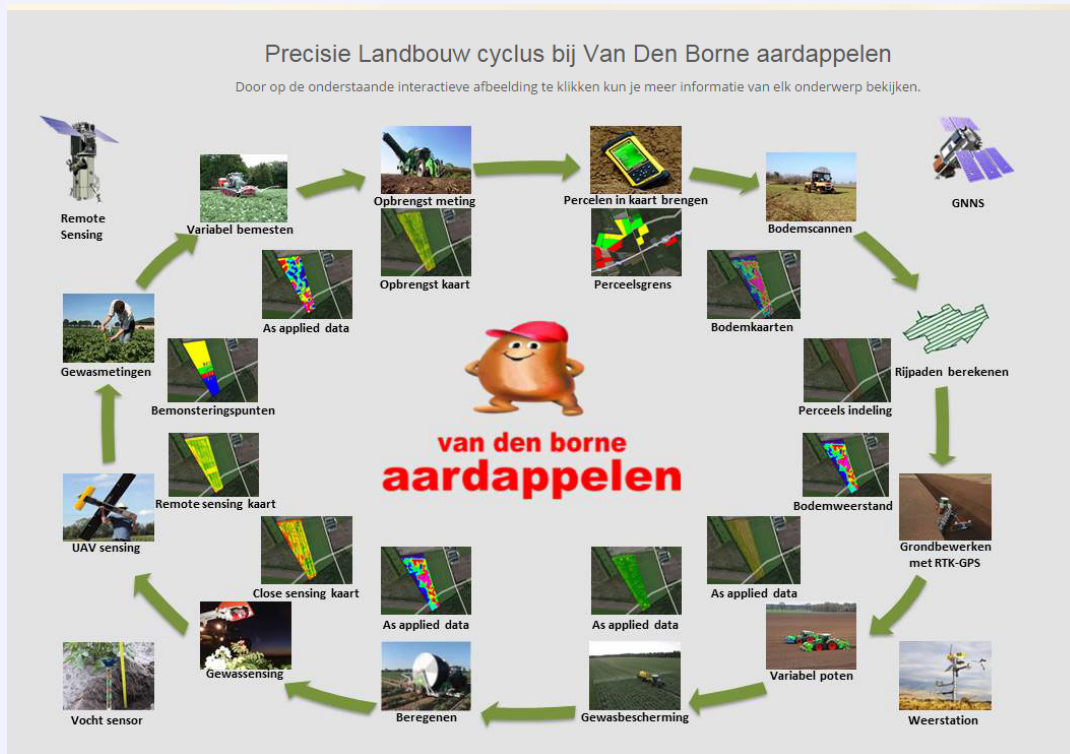


- Service Robots
- Telepresence
- Exoskeleton
- Rehabilitation

### REMOTE PRESENCE DEVICES









## Productivity driven

- Harvesting
- Milking
- Packing
- Processing
- Picking
- Handling

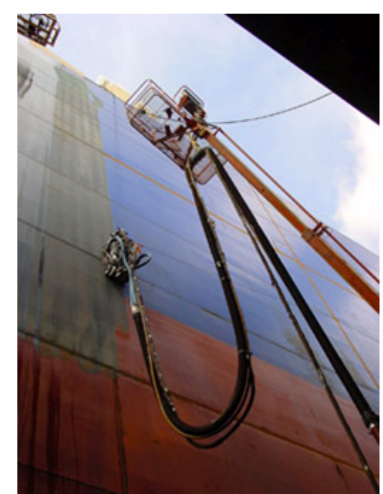
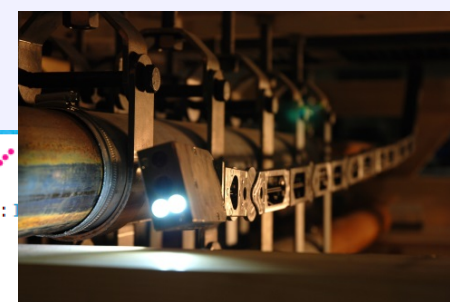


Supporting and assisting in harsh labor and unstructured environment



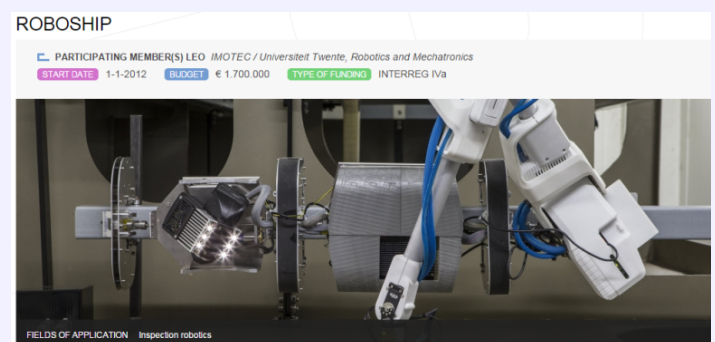
Welkom ◆◆ Nieuws ◆◆ MVP ◆◆ Ki ◆◆  
 [ Kennis- en Innovatie Centrum :: ]

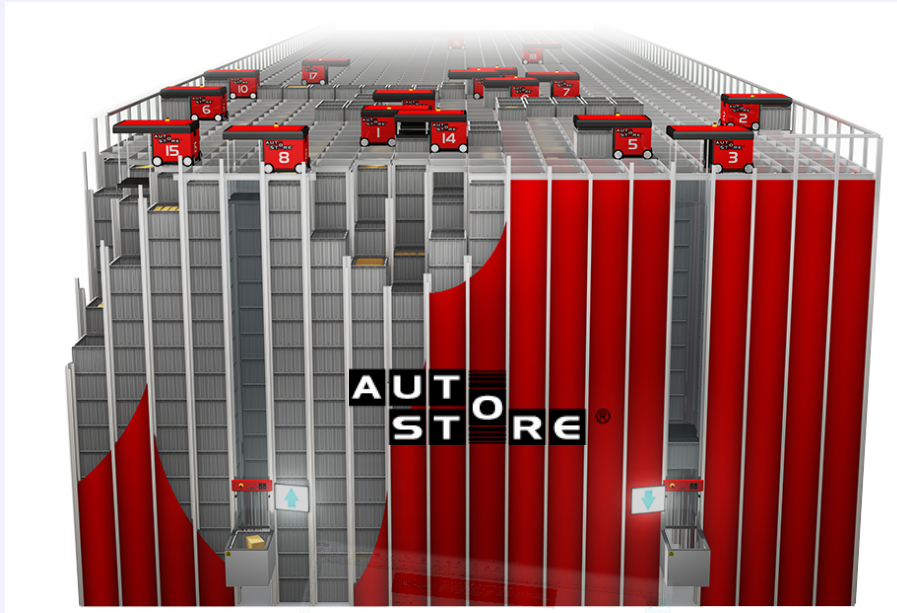
**Ontwikkelen coating robot**



Het ontwikkelen van een coating robot door een automatisch systeem te creëren dat een aanmerkelijke bijdrage zal leveren aan veilig en doelmatig reinigen van grote oppervlaktes.

Voor meer informatie bekijk de [Projectposter Coating Robot](#)





- Drones
- Paro
- Nao and Pepper
- Jibo

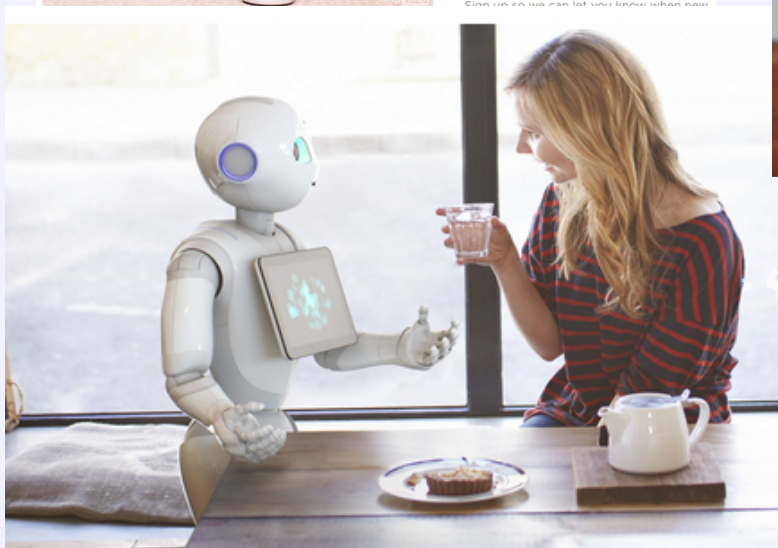
jibo



### Meet JIBO, The World's First Family Robot

We are no longer accepting pre-orders and are focused on getting the first shipment of JIBOs to our early adopters who supported our crowdfunding campaign.

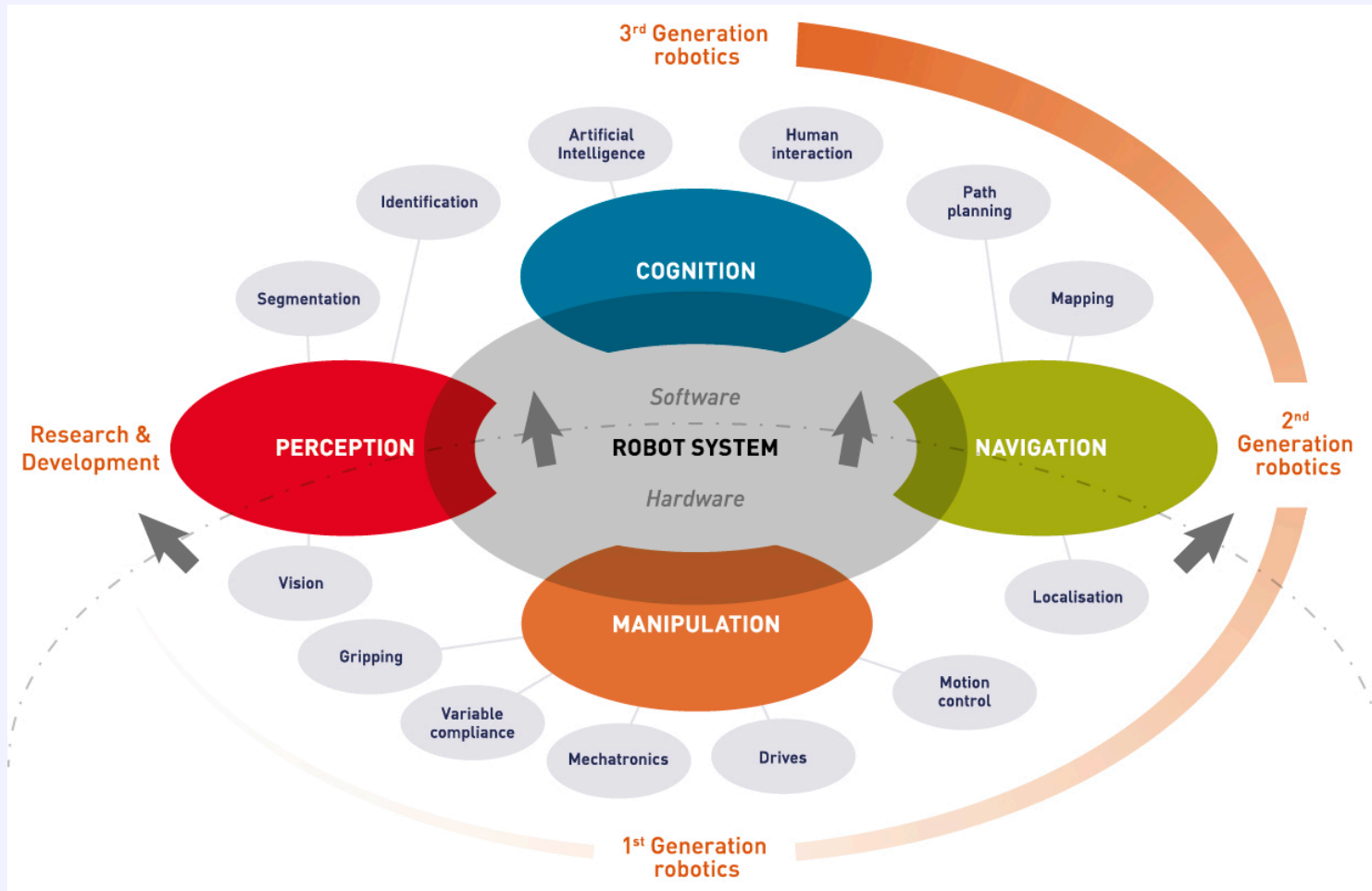
Sign up so we can let you know when new





### Vacuum and Cleaning mass consumer market

- More than 15 brands world wide (*iRobot, Philips, Samsung, Siemens, etc.*)
- More than tens of millions sold



## Trends

- Affordable 3D vision and sensing technology available from gaming industry
- Open software platform ROS increased potential
- Affordable HW solutions

## Challenges

- Perception, Navigation and Cognition
- System integration
- SW & HW limitations
- Fully **addressing application** needs:  
simplicity, costs, reliability, productivity, flexibility, acceptance, safety, TCO

## Darpa Challenge

<https://www.youtube.com/watch?v=fQ6b5Wm5Glw>

 **ROS**



<https://www.youtube.com/watch?v=M8YjvHYbZ9w>

## CO-BOTS GEVEN MEDEWERKERS UITDAGENDER EN MEER GEVARIEERD WERK.

- *OMDAT MEDEWERKERS CO-BOTS TAKEN KUNNEN LEREN (INTERACTIE)*
- *CO-BOTS REPETITIEVE TAKEN UIT HANDEN NEMEN*





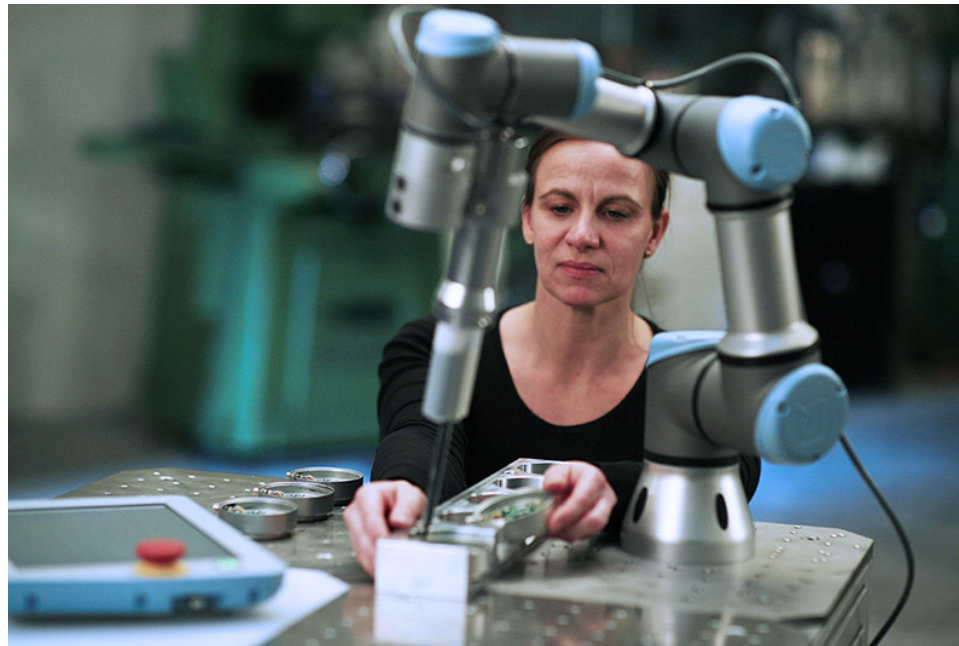
ER ZIJN GEEN NADELEN VAN CO-BOTS VOOR DE  
FYSIEKE BELASTING VAN MEDEWERKER EN ERGONOMIE  
VAN DE WERKPLEK.



CO-BOTS KUNNEN ALLEEN VEILIG NAAST MENSEN  
WERKEN ALS ZE LANGZAMER BEWEGEN DAN MENSEN  
EN DUS ZIJN ZE NIET PRODUCTIEF GENOEG IN DE  
SAMENWERKING MET MENSEN.  
→ KIES MENSEN IPV CO-BOTS



**SOCIALE WERKPLAATSEN KUNNEN INGEWIKKELDERE  
PRODUCTIE AAN DOOR DE SAMEN WERKING VAN CO-  
BOTS MET MENSEN MET EEN HANDICAP.**



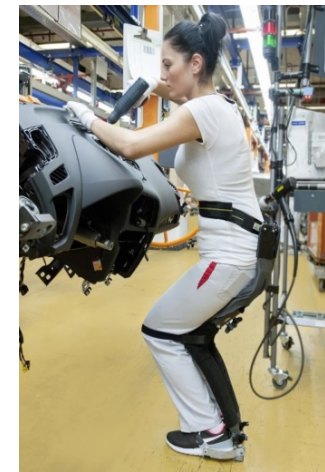
# EXOSKELETONS

## What is an exoskeleton?

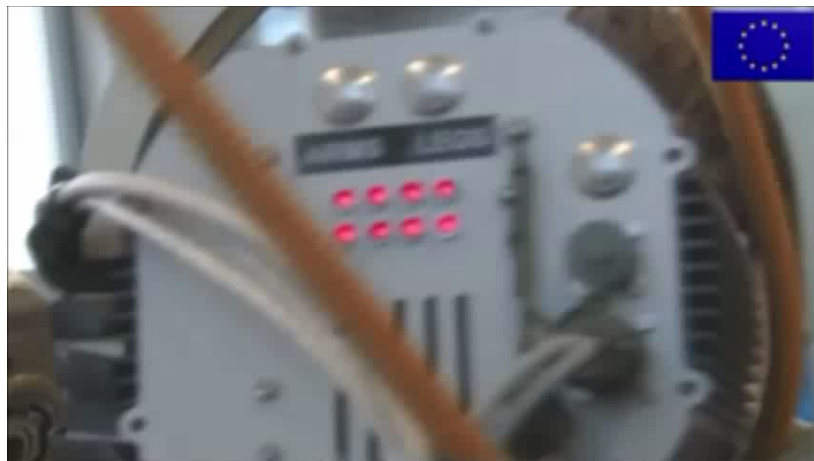
- › Mechanical structure
- › External to the body
- › Wearable
- › Enhance power of a person
- › Human is in charge...

## Variations in..

- › Power supply: passive or active
- › Size: full body, lower body, upper body



## EXAMPLES



## POTENTIAL BENEFIT

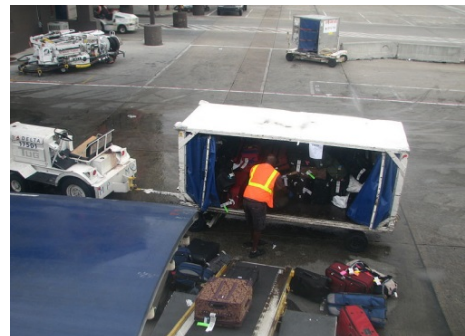
large variation in activities and/or products to be handled is large

human tasks are too difficult or too expensive to automate

exoskeletons, augmenting power to the human body while keeping human flexibility may increase business performance (flexibility, productivity) and promote health

worker is mobile and has to handle loads on many different locations

cranes or balancers are not feasible or effective



# CHALLENGES

- › Benefits are unclear (from health and productivity perspective)
- › Risk of non-acceptance is high
  - › Usability
  - › Discomfort (anthropometry fit, pressure points, climate)
  - › Safety
- › Technical issues
  - › Hindrance of fast and smooth movements
  - › Weight / power source for complete work shifts
  - › Size of device
- › Missing standards for exoskeletons in industry
  - › ISO 13482 on personal care robot safety (not about industry...) (TC 184)
  - › ISO 10218-1 en -2 on industrial robot safety (not about exo-skeletons...)

## RUNNING PROJECT: EU ROBO-MATE

Intelligent exoskeleton based on human robot interaction for manipulation of heavy goods in Europe - Large-scale Integrating EU project (GA 608979)



ZHAW  
CENTRO RICERCHE FIAT  
INDRA SAS  
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MRK  
FRAUNHOFER IAO  
COMPA  
ROPARDO  
ACCELOPMENT





# JOINT INNOVATION CENTER *INTERACTION ROBOTS*

TU Twente & TNO

- › Samenbrengen van kennis
- › Versnellen van innovatieve robotica applicaties
- › Creëren van partnerships
- › Strategic and operational continuity
- › Aanbieden hele waarde keten

# WEARABLE ROBOTS STELLINGEN

## STELLINGEN:

- › Een wearable robot helpt de mens om het maximale uit zich zelf te halen. Optimale belasting van deelsystemen.
- › Een wearable robot stelt meer mensen in staat zwaar werk uit te voeren.
- › Wearable robot is een persoonlijk beschermingsmiddel (Mag alleen worden toegepast als alle andere maatregelen niet mogelijk zijn)
- › Er moet een grens gesteld worden aan de gebruiksduur van een wearable robot om afname van getraindheid te voorkomen.
  
- › User intension is niet door sensoren te detecteren.
- › Een wearble robot mag enig discomfort geven.
- › Extra gewicht (>5kg) van een wearable robot moet naar de grond worden afgesteund.
- › Extra activiteit van andere sterke spiergroepen (bv in de benen) bij het gebruik van een wearable robot is een optimalisatie van de mens.